

L12 - Generative Design

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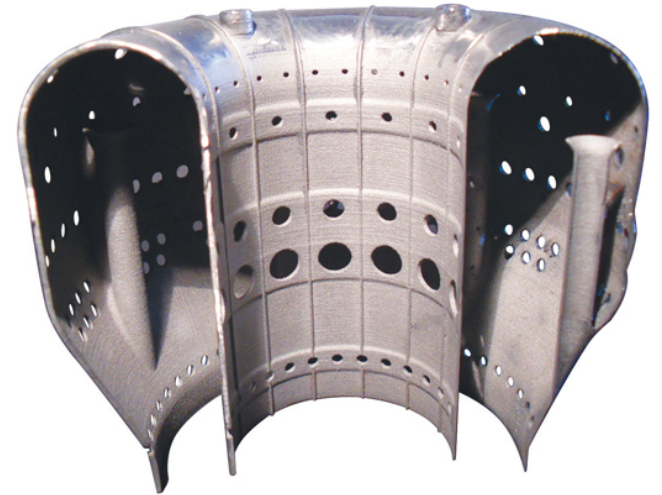
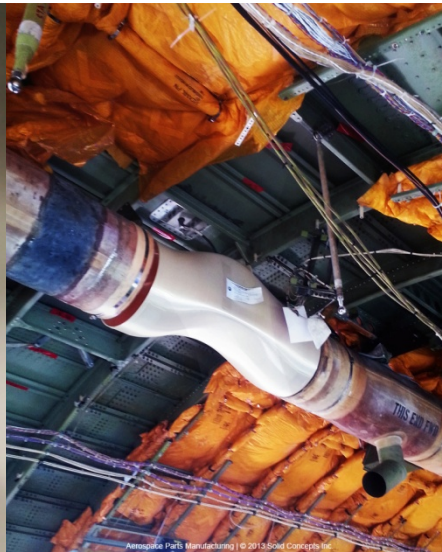
November 24, 2018

Additive Manufacturing

- ▶ Defined by ASTM as:
 - ▶ Process of joining materials to make objects from 3D model data, usually layer upon layer
- ▶ Six Different Types of AM:
 - ▶ Lasers: Stereolithography Apparatus (SLA), Selective Laser Sintering (SLS)
 - ▶ Nozzles: Fused Deposition Modeling (FDM)
 - ▶ Print-heads: Multi-jet Modeling (MJM), Binder-jet Printing (3DP)
 - ▶ Cutters: Laminated Object Modeling (LOM)
- ▶ Mainly used for Rapid Prototyping (Past)
- ▶ More and More used for 'Mass'-Production (Present)



Example of Printed Consumer Products



Boeing Air-Ducting Parts

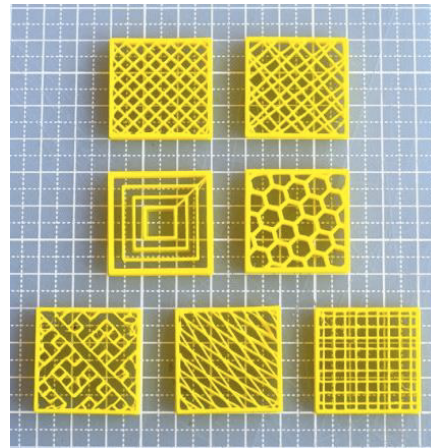
Air-Intake for a Turbine

Lightweight Parts by AM

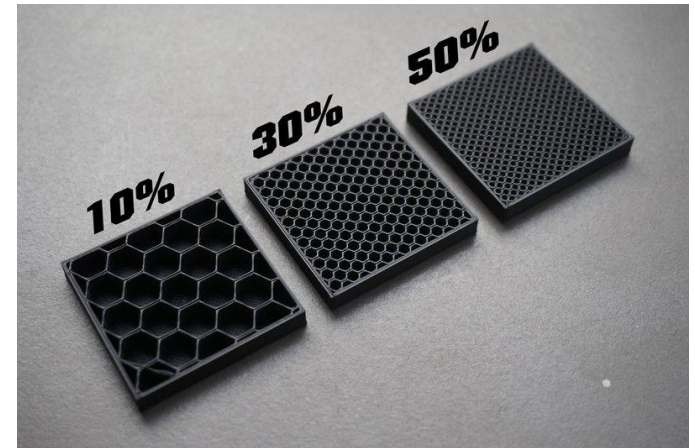
- ▶ Infill structures used to reduce **weight** / **time-cost**
- ▶ Different infill structures are selected **heuristically**
- ▶ Problems:
 - ▶ **Limited types** of patterns
 - ▶ **Not optimized** according to different problems



Regular Uniform Infill



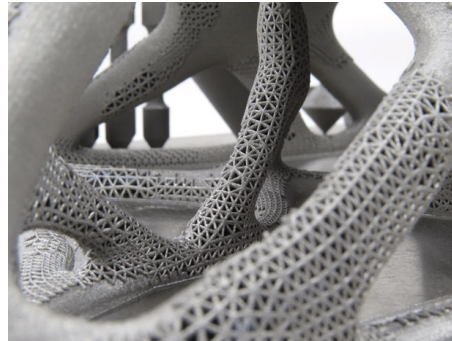
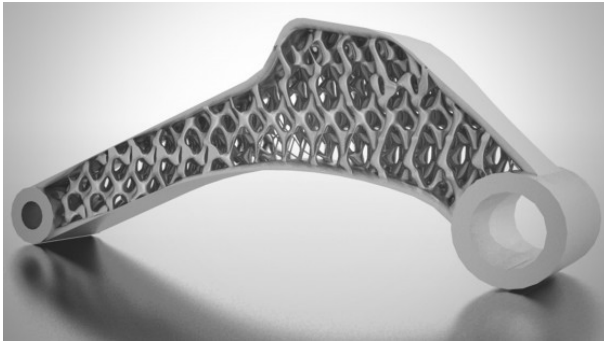
Different Patterns



Different Volumes (by Scaling)

Optimization on Interior Structures

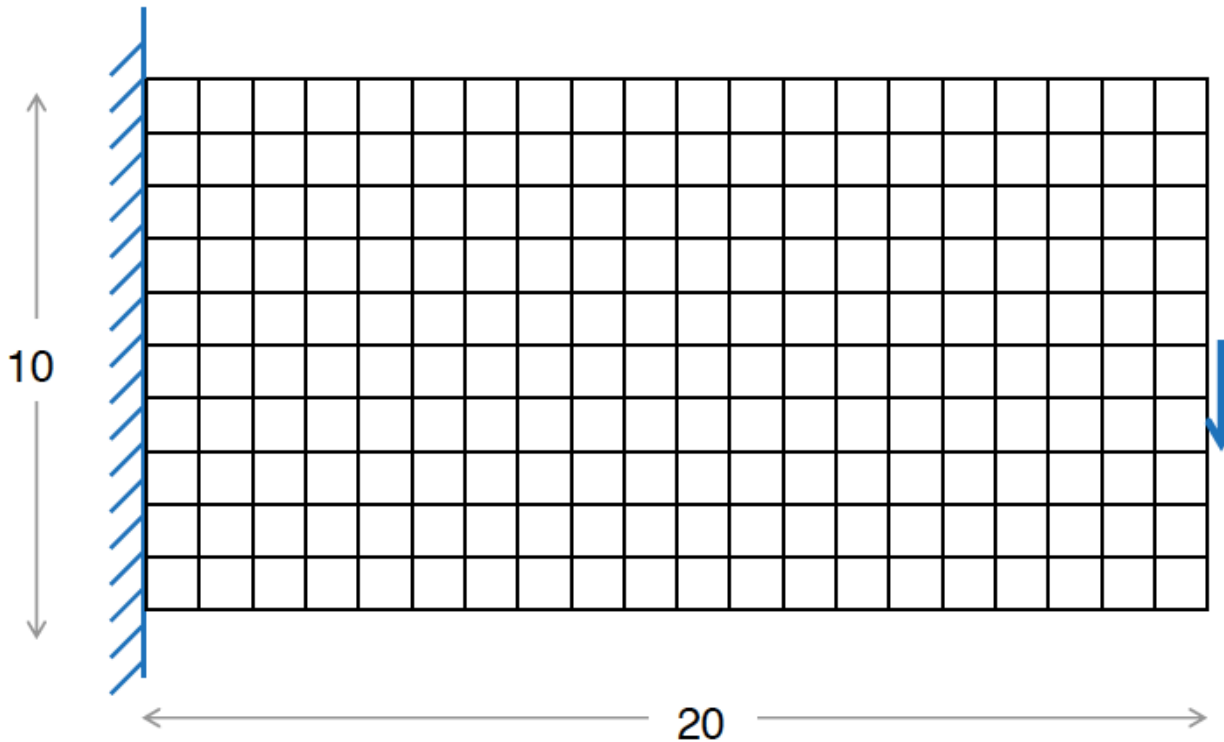
- ▶ A lot of recent work in topology optimization



- ▶ **Problem: Manufacturability?** Especially for infill
- ▶ **Our solution:** by restricting topology optimization to generate structures in a manufacturability-ensured space
 - ▶ Use of grid **refinement** and **grid-to-cell** operators to efficiently perform the optimization
 - ▶ Optimization of **mechanical stiffness** and **static stability** effectively and efficiently

Framework of Topology Optimization

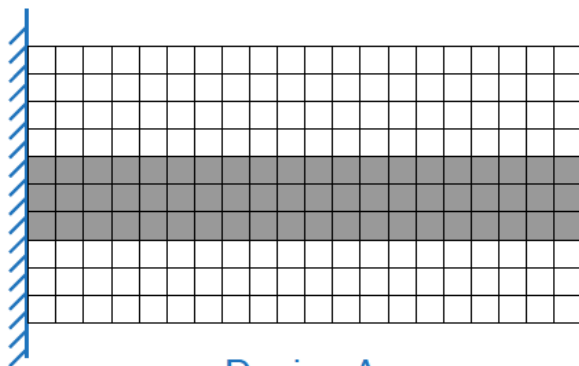
- ▶ Design a stiffest shape by placing 60 LEGO blocks
 - ▶ **60?** as smallest number as possible (i.e., **lightweight** demand)



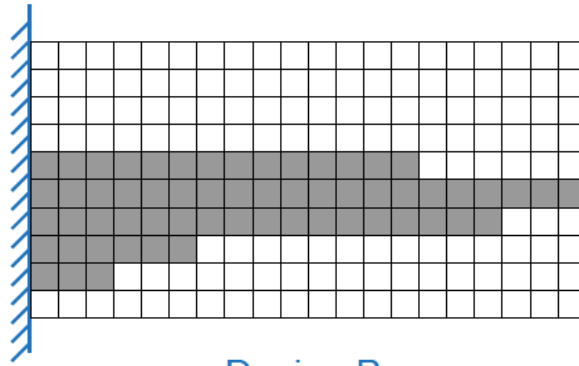
Bone Chair
by Joris Laarman

A Toy Example: Possible Choices

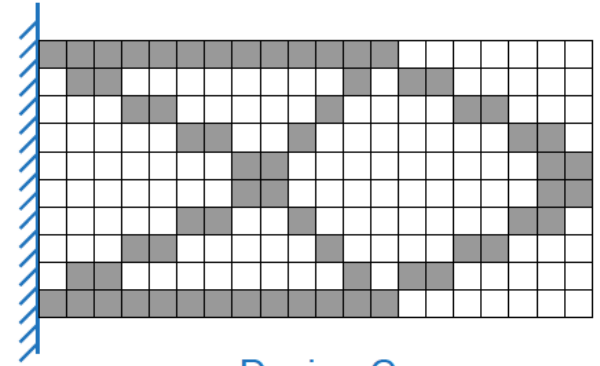
- ▶ Number of possible designs: $C_{200}^{60} = 7.04 \times 10^{51}$
- ▶ Which one has the highest stiffness?



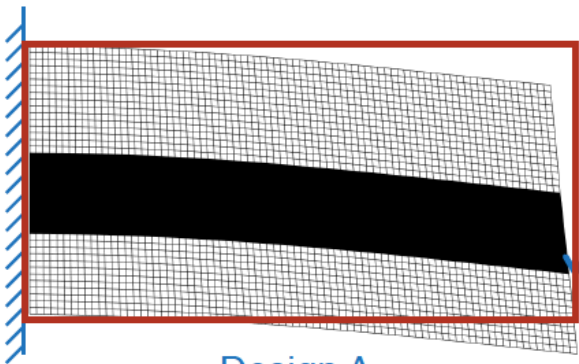
Design A



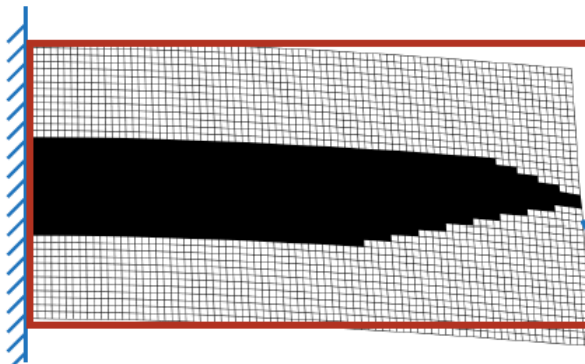
Design B



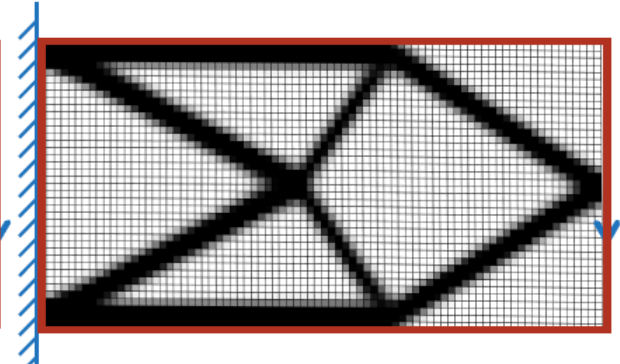
Design C



Design A



Design B



Design C

Framework of Topology Optimization

- ▶ Topology optimization for **minimizing** the **strain energy**

$$\begin{aligned} & \underset{\beta}{\text{minimize}} && E = \frac{1}{2} u^T K(\rho) u, \\ & \text{subject to} && K(\rho) u = f, \\ & && V(\rho) = \sum_e \rho_e \leq V^*, \\ & && \rho_e(\beta) = \begin{cases} 1.0 & e \in \text{solid}, \\ \rho_{min} & e \in \text{cavity}, \end{cases} \\ & && \beta_c \in \{0, 1\}, \forall C. \end{aligned}$$

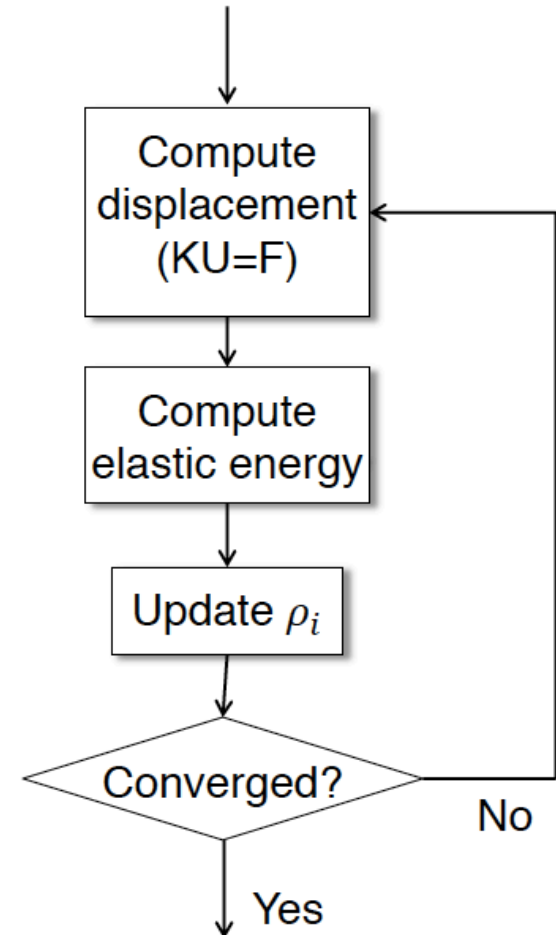
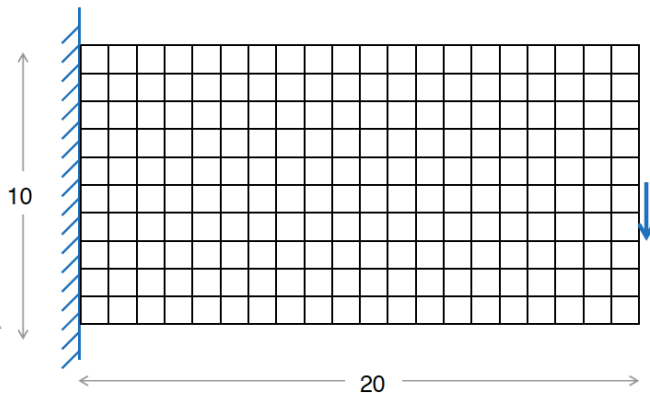
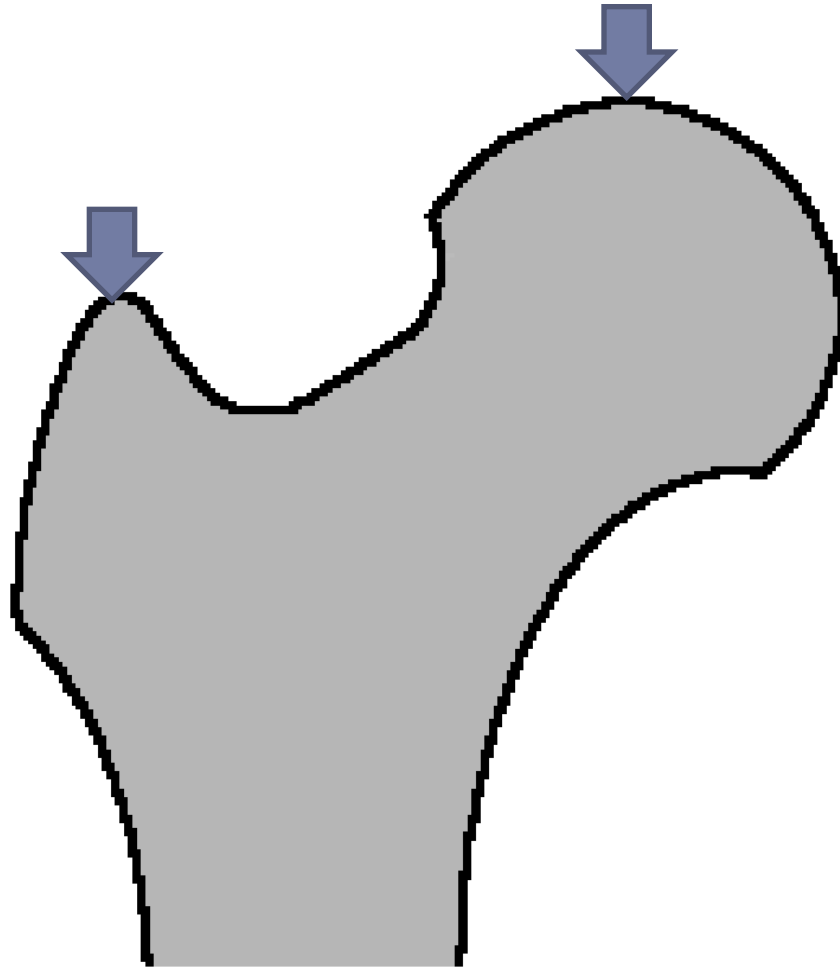
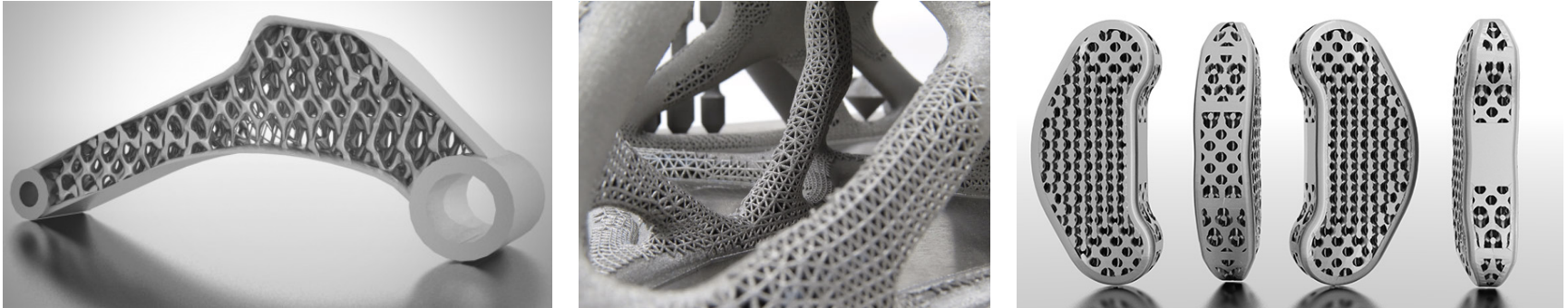


Illustration of Topology Optimization



Optimization on Rhombic Structures

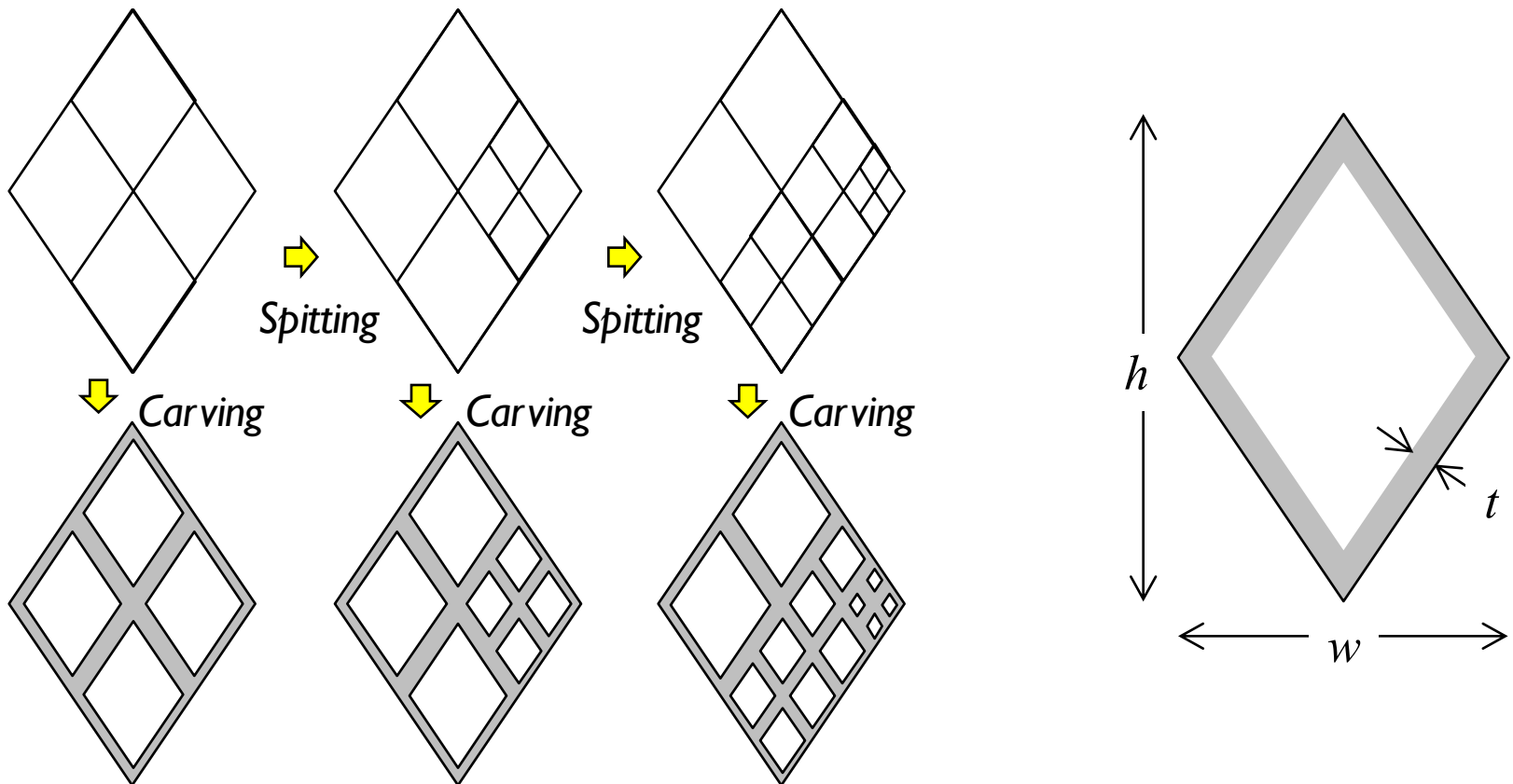
- ▶ A lot of recent work in topology optimization



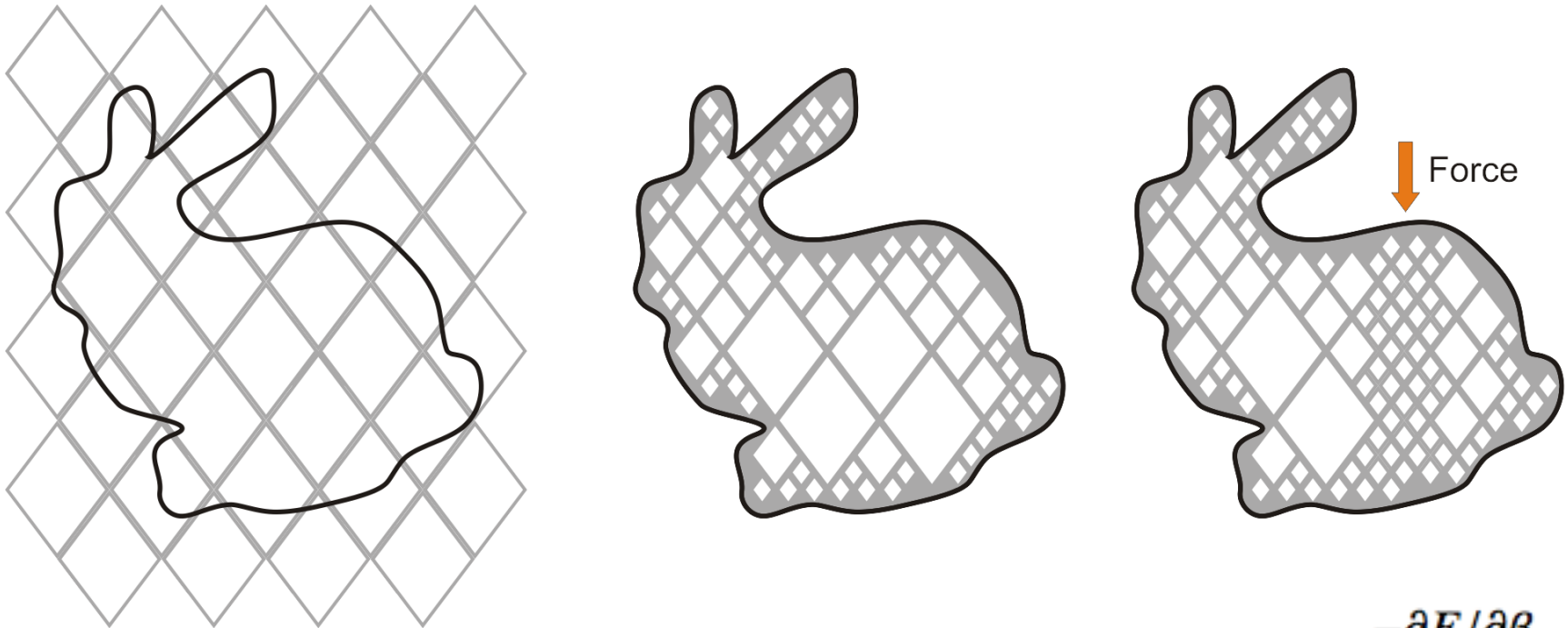
- ▶ **Problem: Manufacturability?** Especially for infill
- ▶ **Our solution:** by restricting topology optimization to generate structures in a manufacturability-ensured space
 - ▶ Use of grid **refinement** and **grid-to-cell** operators to efficiently perform the optimization
 - ▶ Optimization of **mechanical stiffness** and **static stability** effectively and efficiently

Adaptive Subdivision and Dual-Rep.

- ▶ Manufacturability can be ensured by the geometric setting: *Slope Angle* and *Wall Thickness*



Flow of Optimization by Refinement

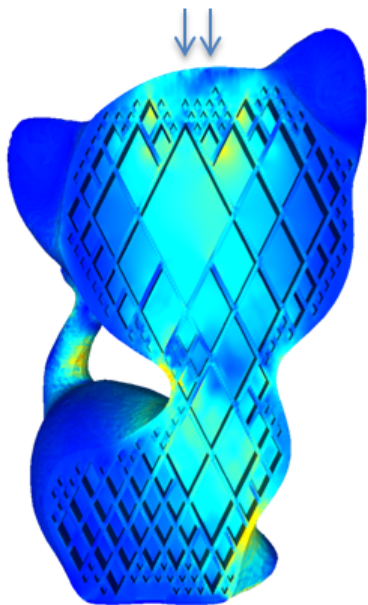
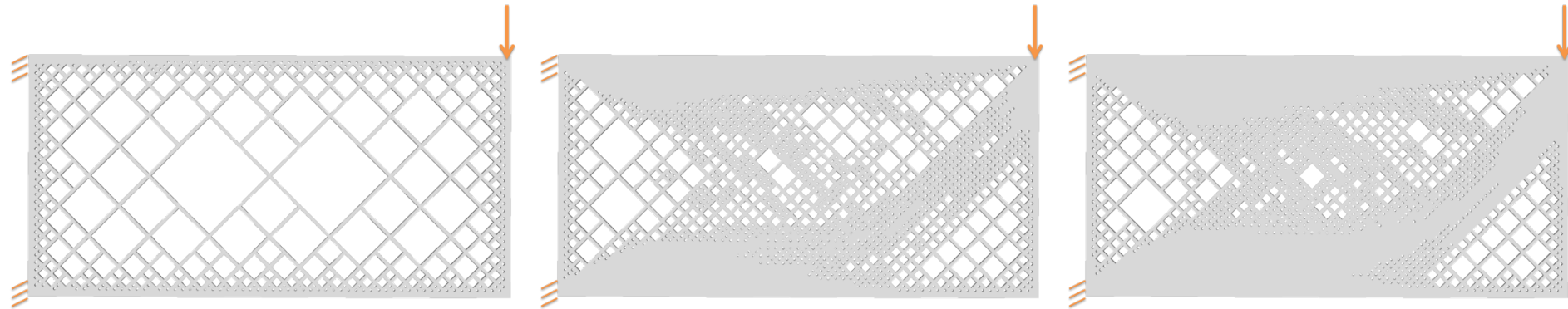


► An iterative process by sensitivity analysis:

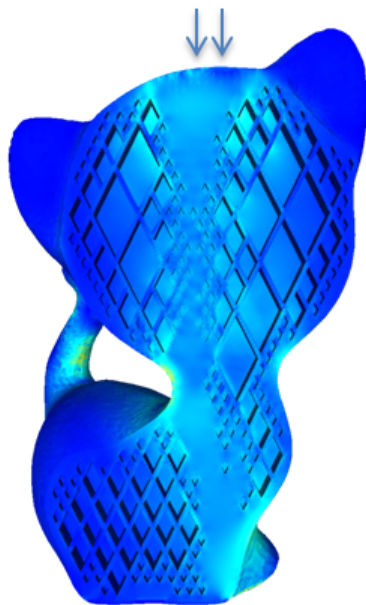
$$G_c = \frac{-\partial E / \partial \beta_c}{\partial V / \partial \beta_c}$$

1. Finite Element Analysis of elasticity
2. Evaluate the sensitivity
3. Update the rhombic structure by subdividing selected cells

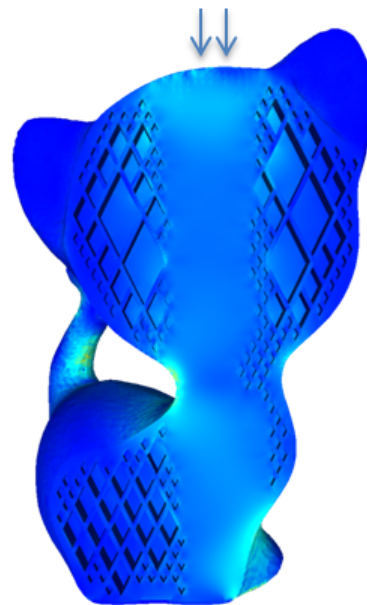
Self-Supporting Infill Optimization



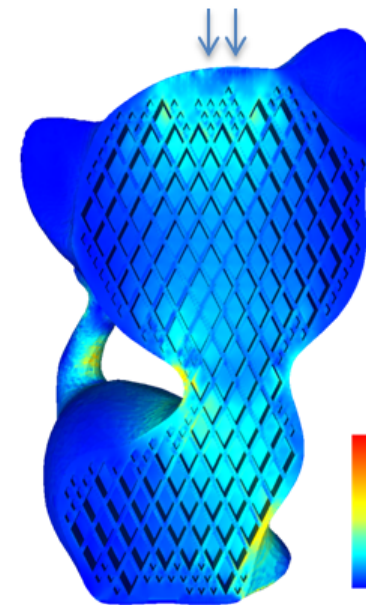
$V/V_{solid} : 60.0\%$



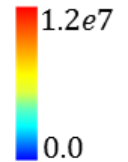
$V/V_{solid} : 66.0\%$



$V/V_{solid} : 69.8\%$

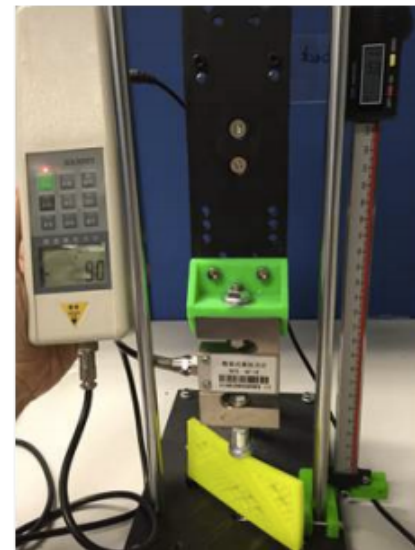
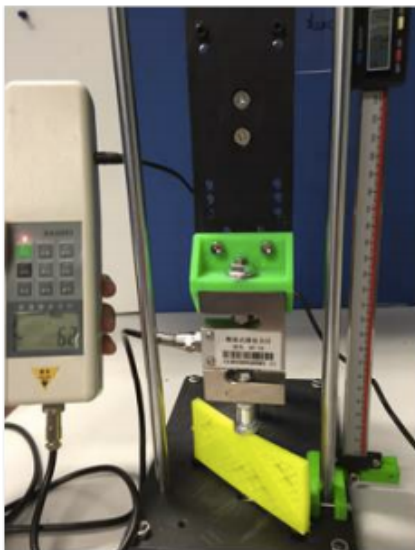
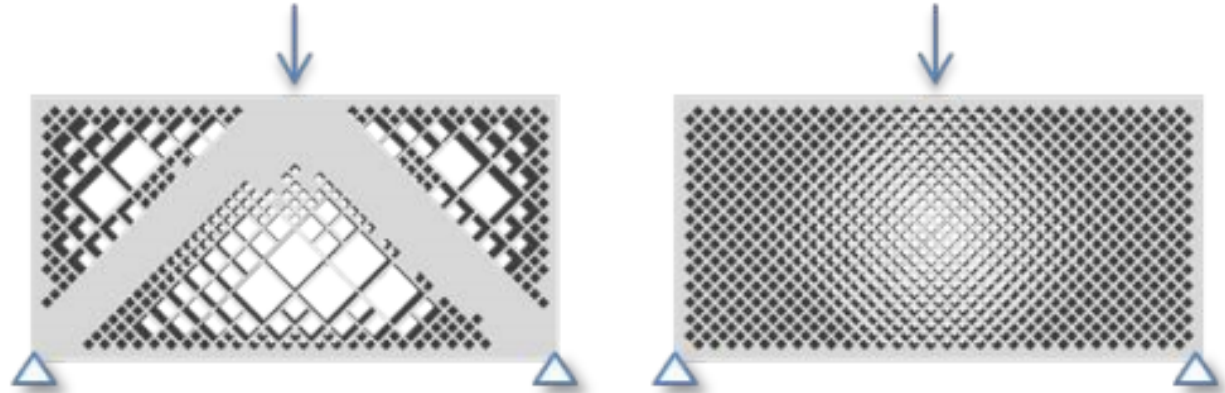


$V/V_{solid} : 67.9\%$



Optimization of Infill Structures

- ▶ Physical Tests
(for comparison)



Applying the same loading (2.11 vs 4.08mm)

Under the same displacement (3mm)

Formulation: Static Stability

- ▶ Defining an energy to move the **center of gravity**, \mathbf{c}_g , into the **convex hull** of **contacted point** on the ground
- ▶ A **weak form** formulation using center of convex hull, \mathbf{c}_h

$$\begin{aligned} & \underset{\beta}{\text{minimize}} && E_s = \|(c_g - c_h)^{\perp g}\|_2^2, \\ & \text{subject to} && \beta_c \in \{0, 1\}, \forall C. \end{aligned}$$

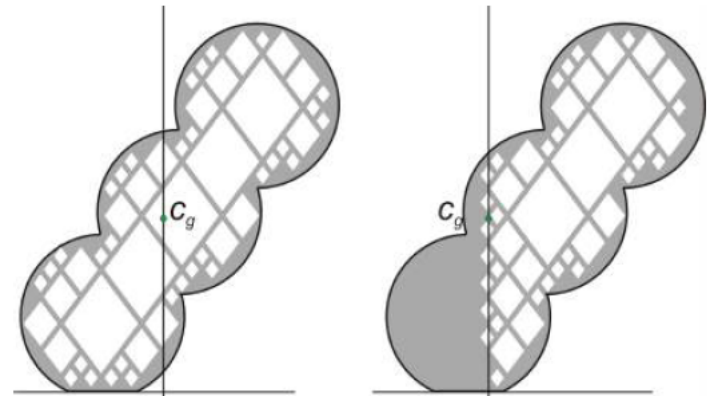
The gradient

$$\frac{\partial E_s}{\partial \beta_c} = \frac{2m_c}{m_c + m_g} \left[(c_g - c_h)^{\perp g} \cdot (c_c - c_g)^{\perp g} \right]$$

m_c : the center of mass **after refining** a considered cell

m_g : the **current center** of mass

c_c : the **geometric center** of the cell under consideration

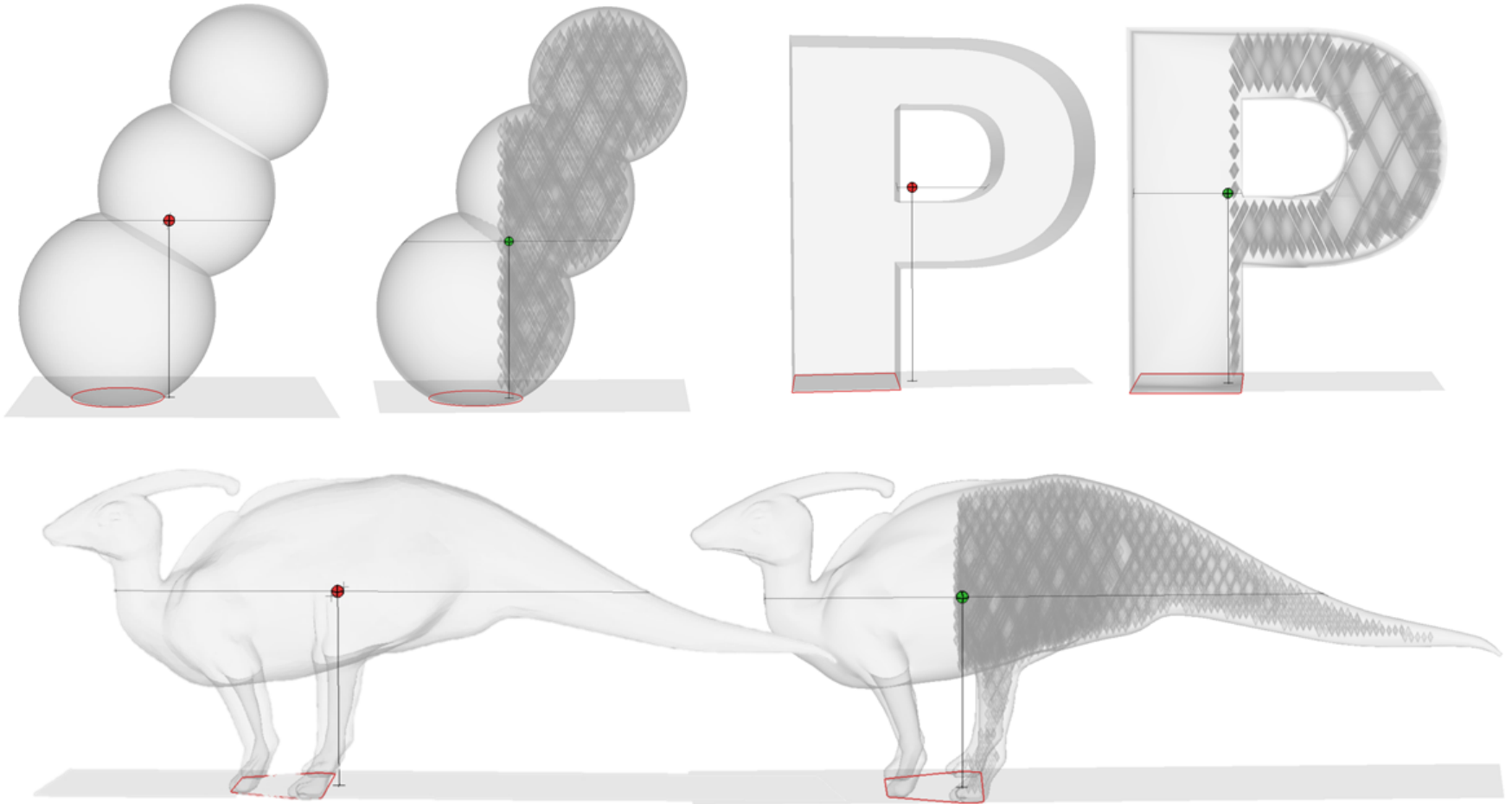


Negative is moving towards the center \mathbf{c}_h

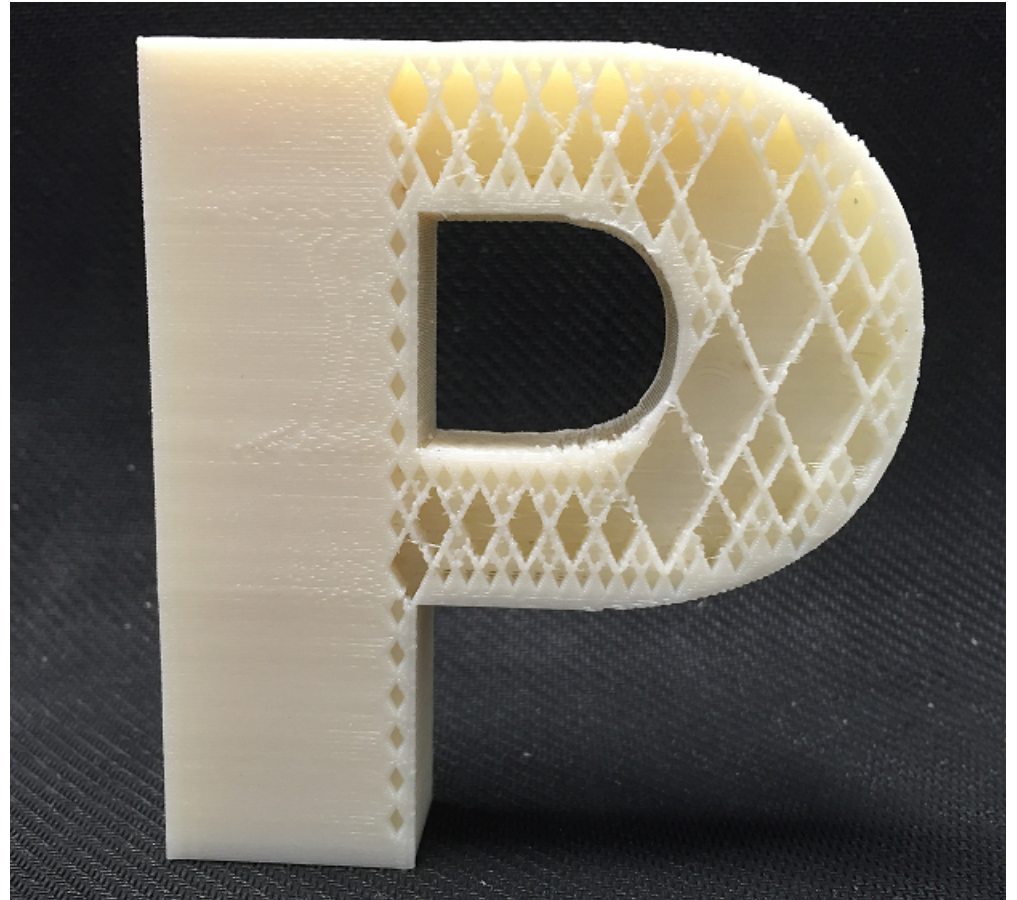
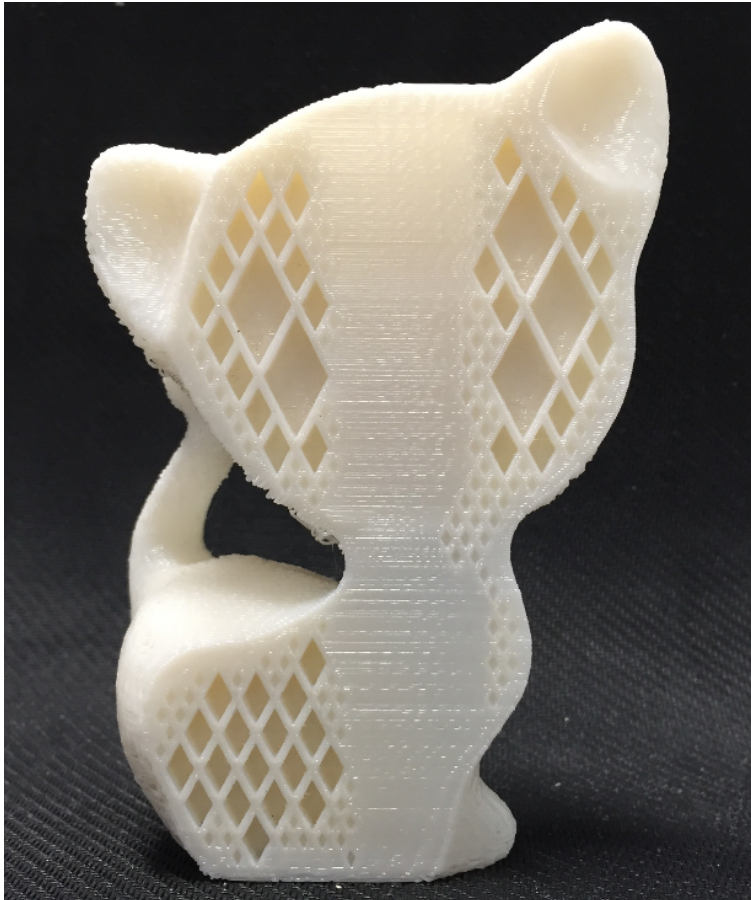
Sort candidate cells in **ascending** order

Refine one by one

Infill Optimization for Static Stability



Self-Supporting Infill Optimization



Jun Wu, Charlie C.L.Wang, Xiaoting Zhang, and Rudiger Westermann, "Self-supporting infill optimization on rhombic cells", *Computer-Aided Design*, 2016.

Conclusion Remarks

- ▶ An infill optimization approach ensures **manufacturability explicitly**
 - ▶ By restricting optimization to generate **rhombic structures**
 - ▶ **Overhang constraint** and **minimal-wall constraint** are seamlessly satisfied
 - ▶ Validated in both **mechanical stiffness** and **static stability** problems
- ▶ Open questions:
 - ▶ Greedy approach – **no guarantee** of **global** optimality
 - ▶ What about allowing **boundary** to deform? within **controlled region**?
 - ▶ **More sparse** self-supporting structures?
 - ▶ Current - minimizing compliance, how about **other objectives**?
 - ▶ Maximizing compliance?
 - ▶ Constraints on maximum stress?