

Computational Fabrication:

From Design Automation to New Manufacturing

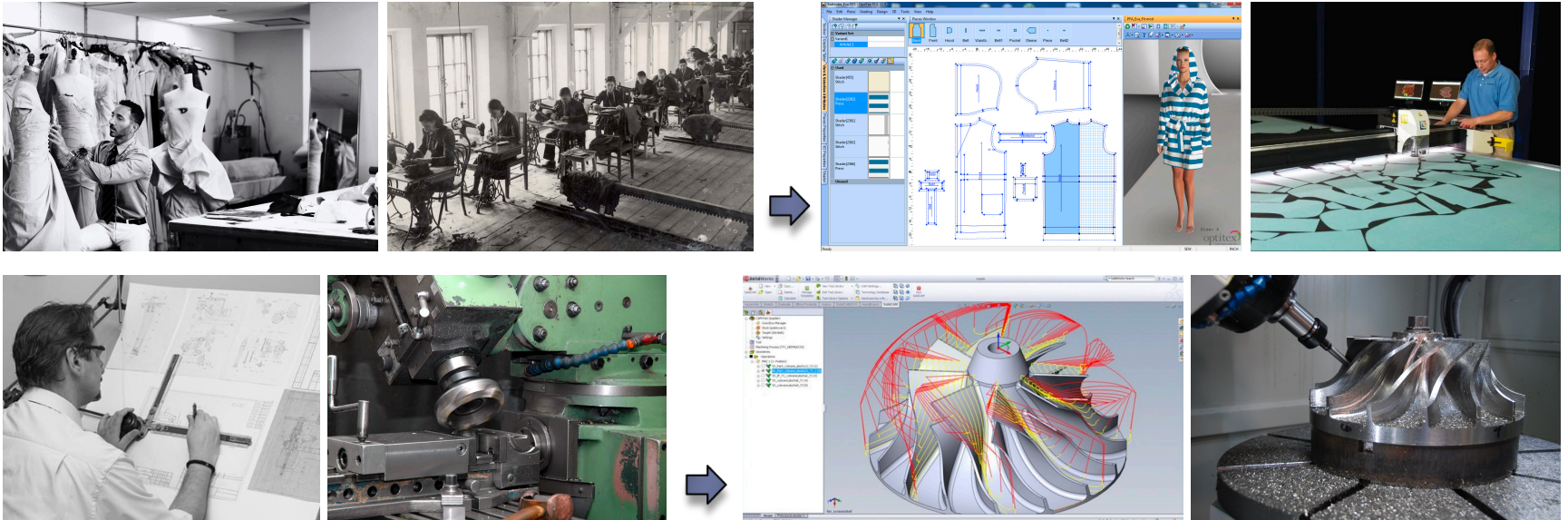
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December 3, 2018

Computational Design & Manufacturing

- ▶ History can be traced back to 1970s
 - ▶ How to advance **conventional** production?
 - ▶ Make it **better, faster** and **more economical**
 - ▶ Revolution of conventional industrial by **Digitization**
 - ▶ How about **future?**



Computational Design and Fabrication

CAD \neq **C**omputer-**A**ided **D**rafting

CAD \neq **C**omputer-**A**ided **D**ocumentation

- ▶ **Demand:** **tools** completely integrated into the **process of design** practice
 - ▶ Automatic design process (**Design Automation**)
 - ▶ Design better products (**Design Optimization**)
 - ▶ Called **Generative Design** in Industry (e.g.,Autodesk)
- ▶ **Our vision** in **A**dvanced **D**esign and **M**anufacturing
 - ▶ Making the design process more **automatic**, **intelligent** and **systematic**
 - ▶ Solving **manufacturing problems** at the **design** phase
- ▶ **Our focus:** inventing advanced **computational tools** to face the grand challenges of **design** and **manufacturing**

Computational Design and Fabrication

Design

Automation

Design

Optimization

Direct Digital

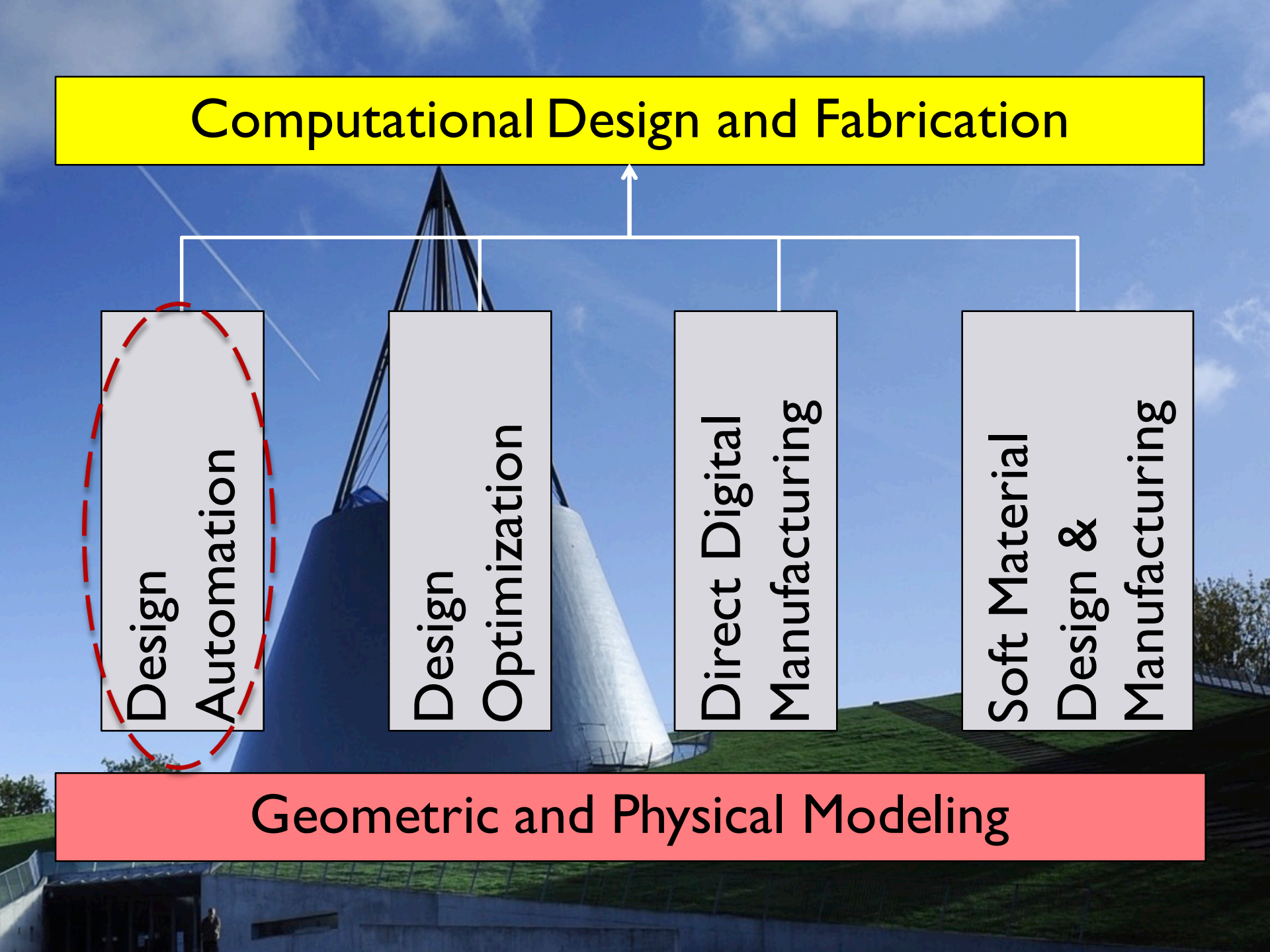
Manufacturing

Soft Material

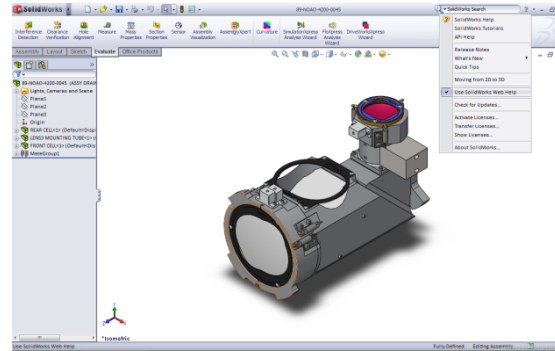
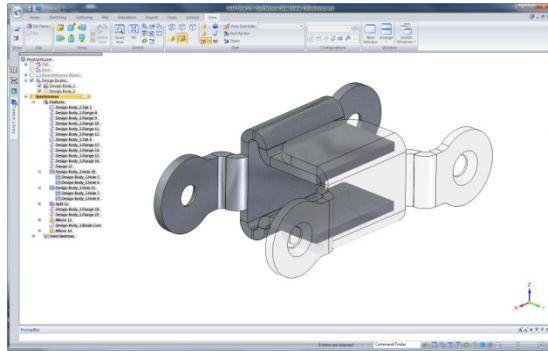
Design &

Manufacturing

Geometric and Physical Modeling



Design Automation: Ultra Personalized Products Driven by Body Shape

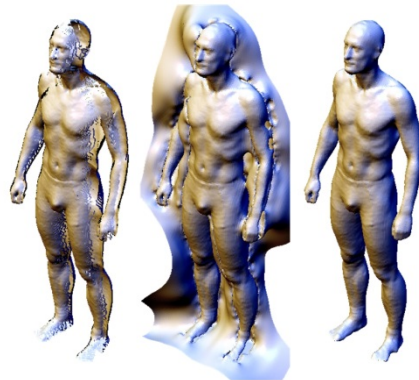
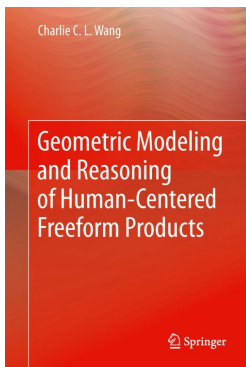
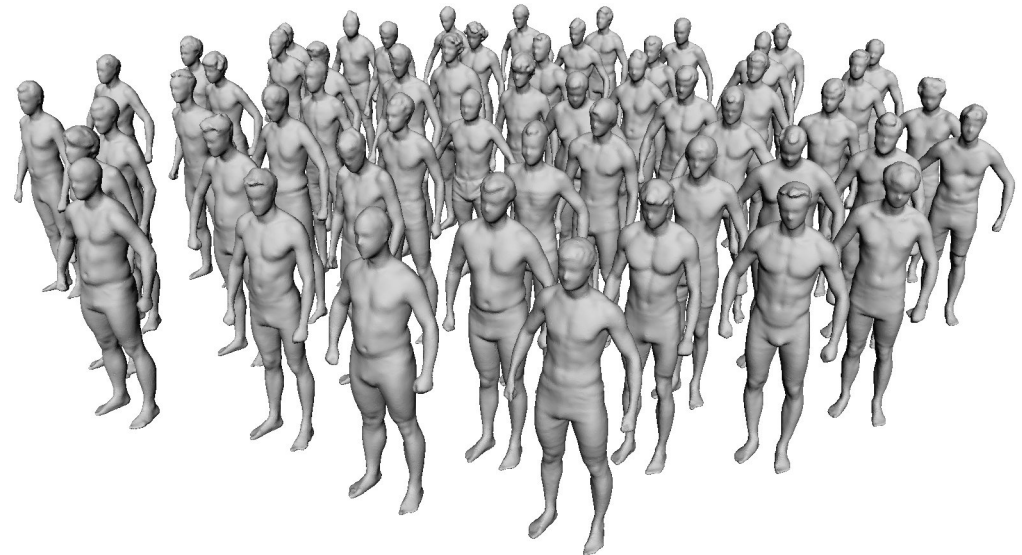
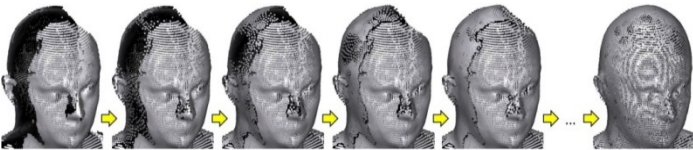
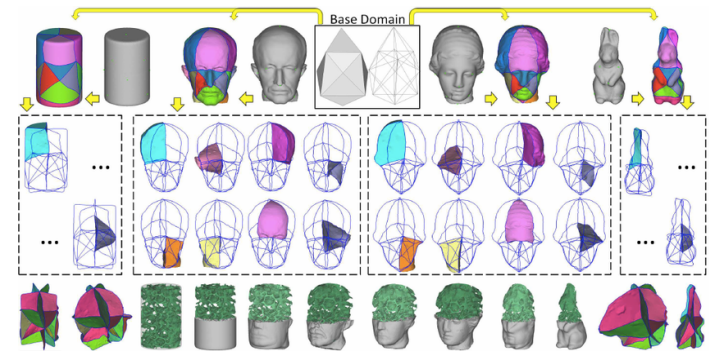
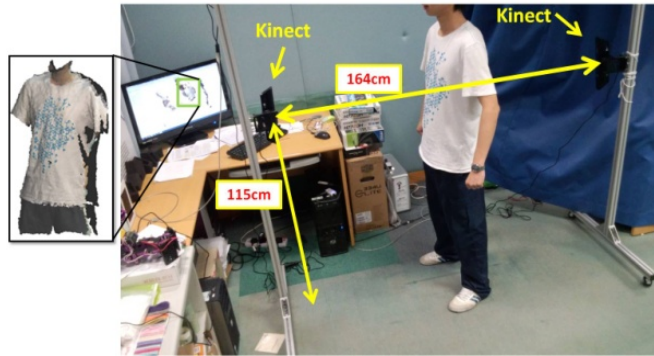


- ▶ Design automation in commercial CAD/CAM systems (parametric design)
 - ▶ Developed for products with **regular shape**
 - ▶ Usually driven by **dimensional parameters**
- ▶ Technology has been developed for overcoming these challenges – shape drive design automation
 - ▶ **Consistent** modeling of digital human bodies
 - ▶ Encoding/decoding the spatial relationship between **human body** and **product**
 - ▶ Geometric optimization for **fabrication**

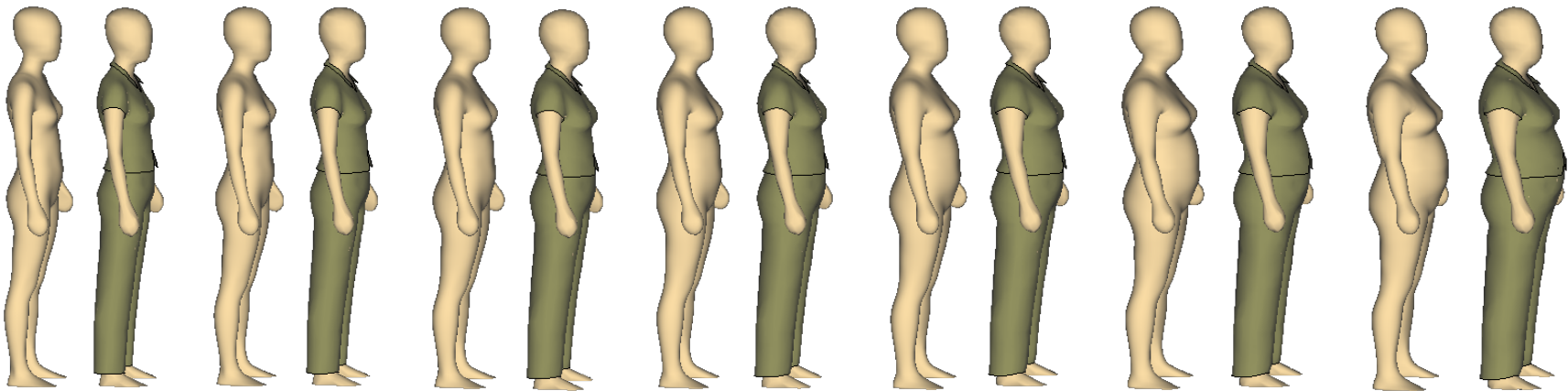
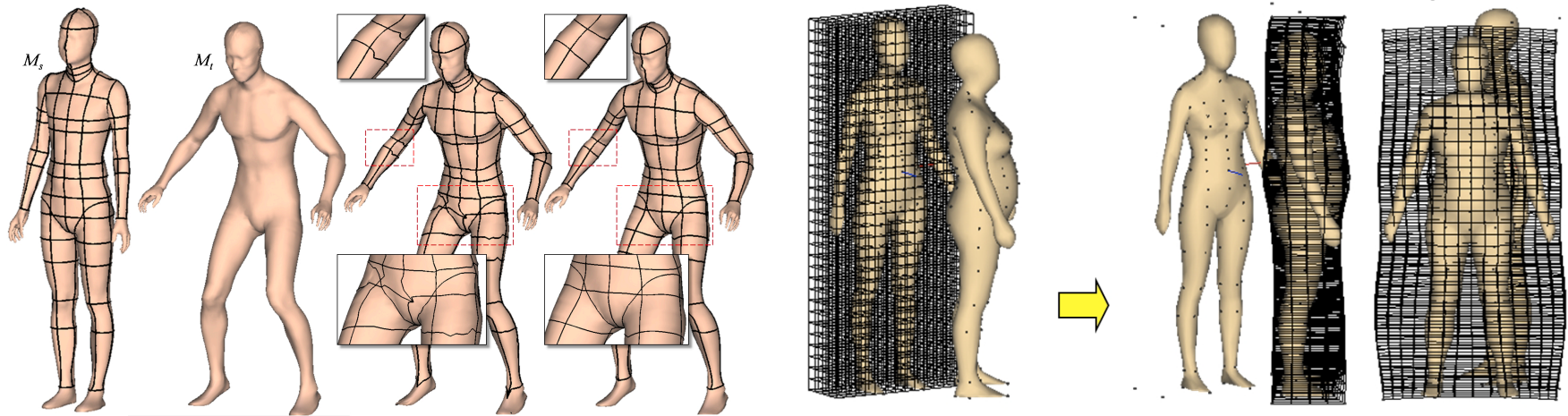


Exoskeleton as a future product: **freeform geometry** and **conformal** to the shape of human body

Design Automation: Consistent Modeling of Digital Human Bodies



Design Automation: Design Transfer for Wearable Products



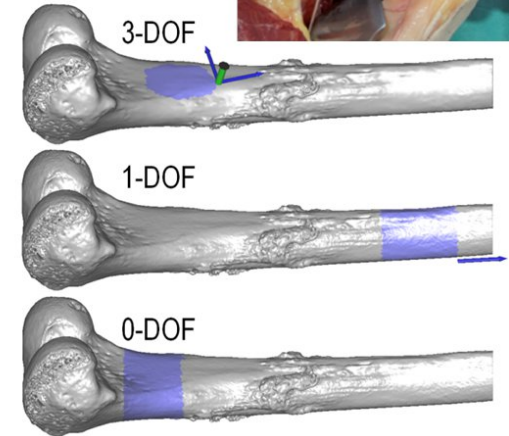
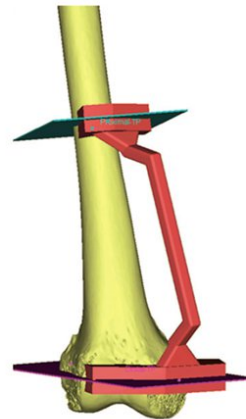
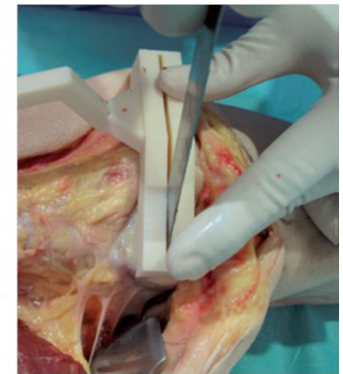
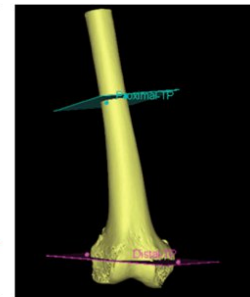
Charlie C.L. Wang, K.-C. Hui, and K.M. Tong, "Volume parameterization for design automation of customized free-form products", *IEEE Transactions on Automation Science and Engineering*, 2007.

Design Automation for Personalized Wearable Products



Design Automation: Searching for 'Best'-Fit is General for All Wearable Instruments

- ▶ Computing **unique** footprint to align the image / patient **coordinate systems** – **P**atient **S**pecific **I**nstruments (**PSI**)
- ▶ Preoperatively **planned resection path** can be **precisely** realized



Computational Design and Fabrication

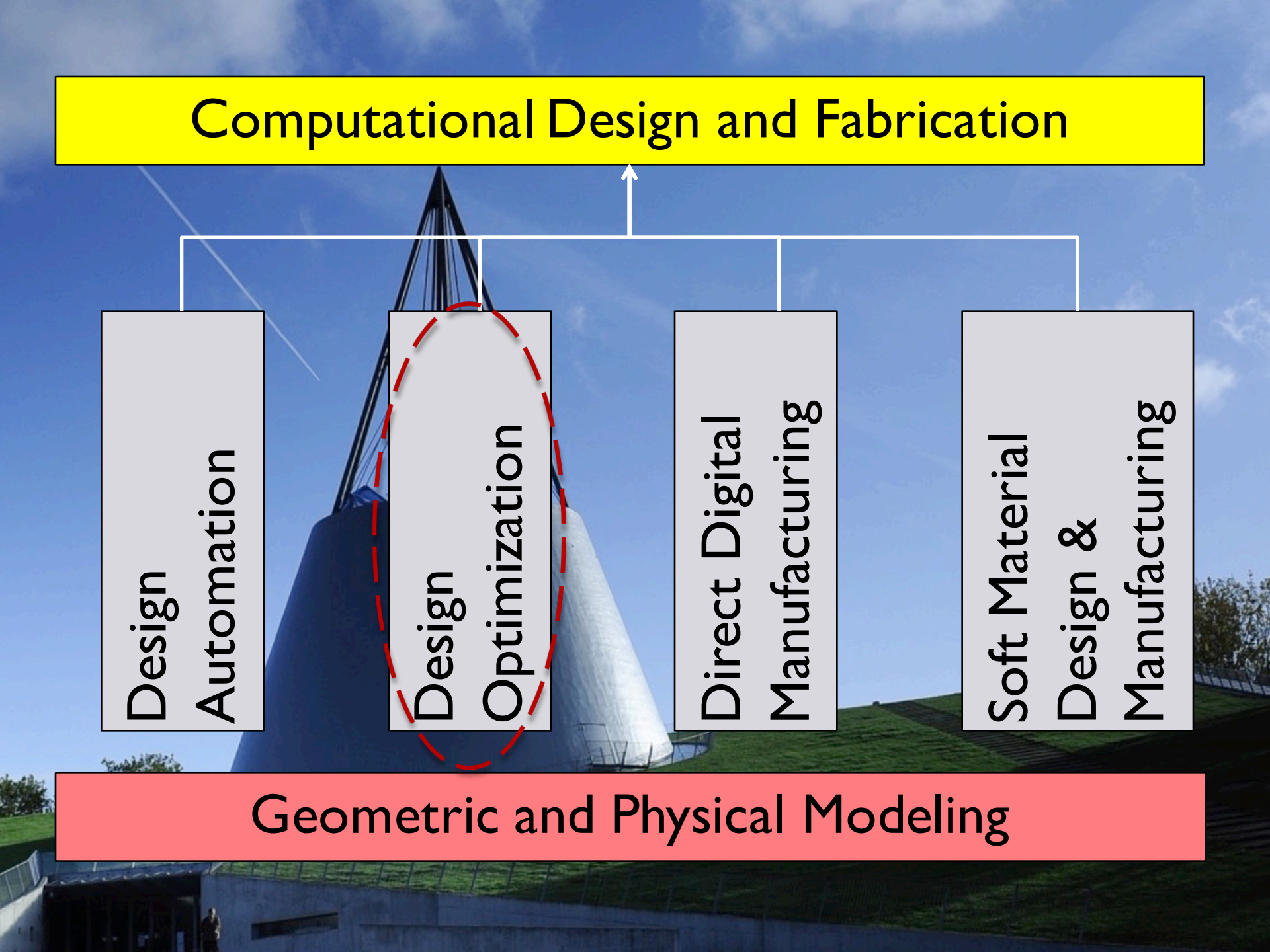
Design
Automation

Design
Optimization

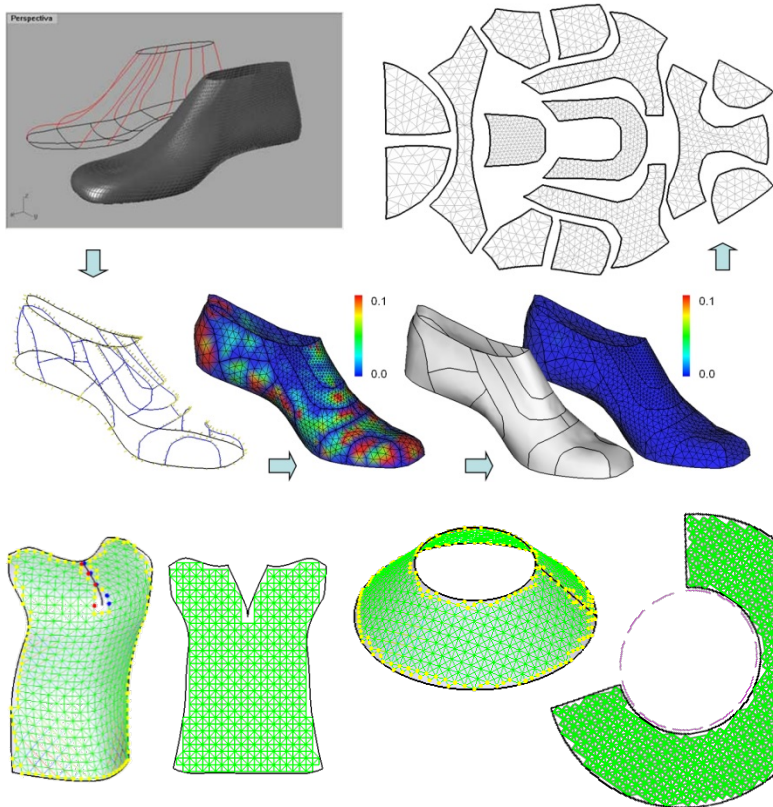
Direct Digital
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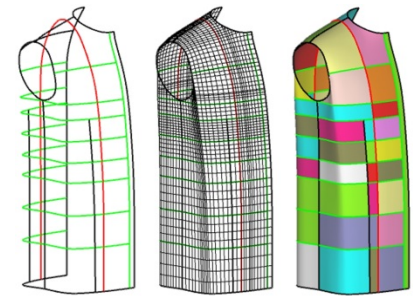
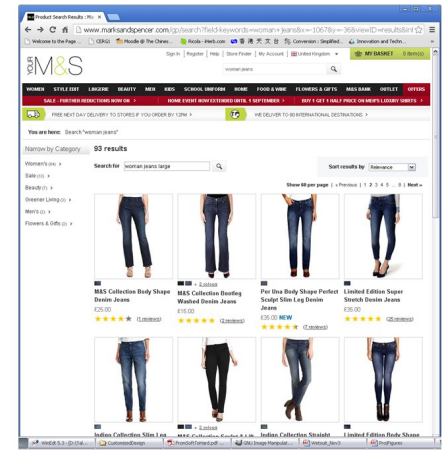
Geometric and Physical Modeling



Design Optimization for Manufacturing (i): Flattening Solution for Planar Materials



WireWarping++



- Charlie C.L. Wang, "Methods for Flattening a 3D Surface into a 2D Piece", U.S. Patent 8,411,090, April 2, 2013.
- Yunbo Zhang, and Charlie C.L. Wang, "WireWarping++: Robust and flexible surface flattening with length control", *IEEE Transactions on Automation Science and Engineering*, vol.8, no.1, pp.205-215, 2011.
- Charlie C.L. Wang, "Towards flattenable mesh surfaces", *Computer-Aided Design*, vol.40, no.1, pp.109-122, 2008.

Design Optimization for Manufacturing (ii): Flattening Solution for Glass Production



Figure 77: Mould of variation 2



Figure 78: Result of variation 2



Figure 83: Mould of variation 5



Figure 84: Result of variation 5



Figure 79: Mould of variation 3



Figure 80: Result of variation 3

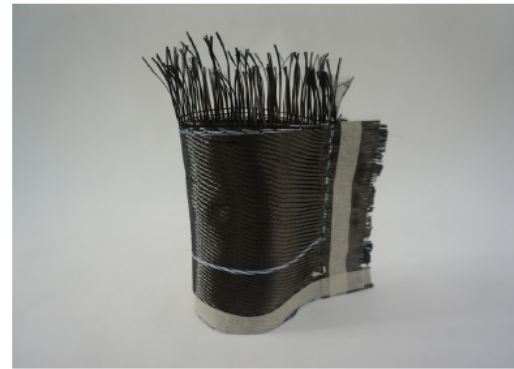


Figure 85: Mould of variation 6



Figure 86: Result of variation 6

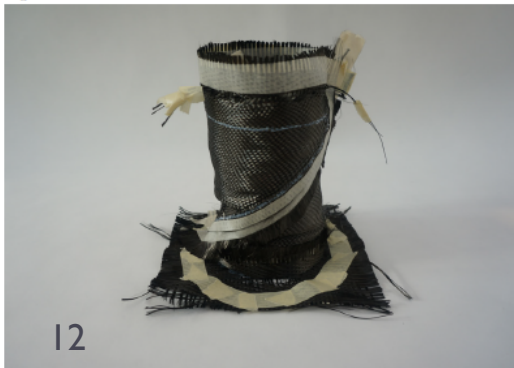


Figure 81: Mould of variation 4



Figure 82: Result of variation 4

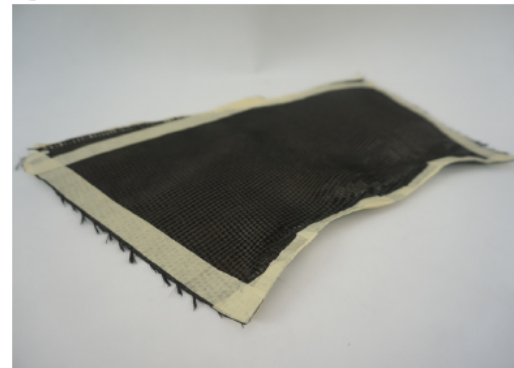


Figure 87: 'Mould' of variation 7



Figure 88: Result of variation 7

Design Optimization for Manufacturing (ii): Flattening Solution for Glass Production

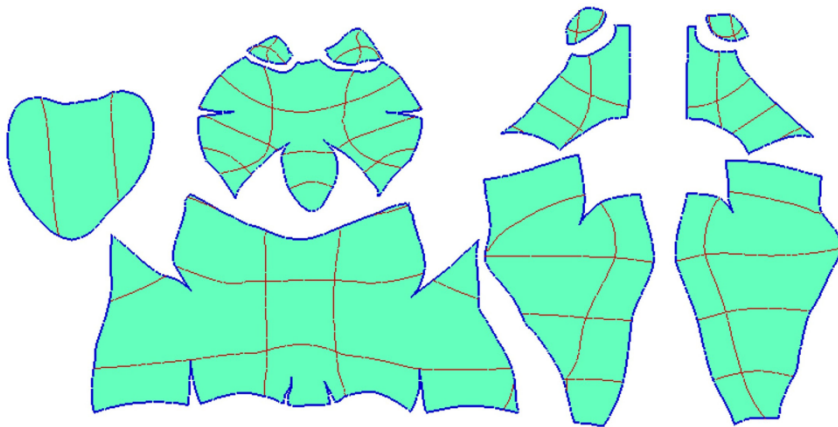
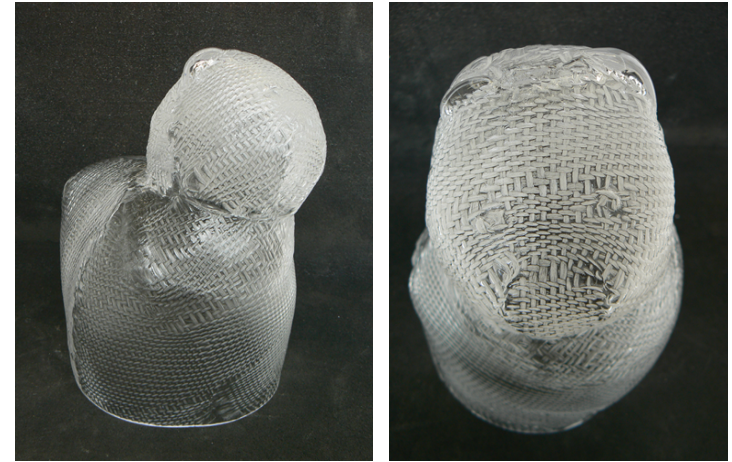
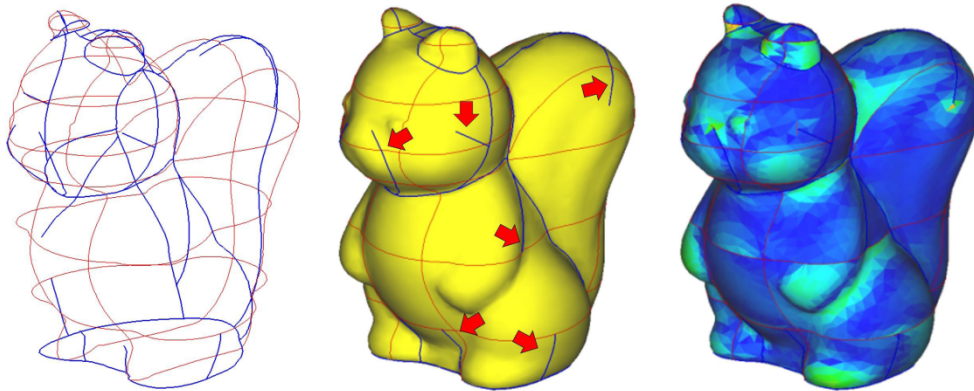


Design Optimization for Manufacturing (ii): Flattening Solution for Glass Production

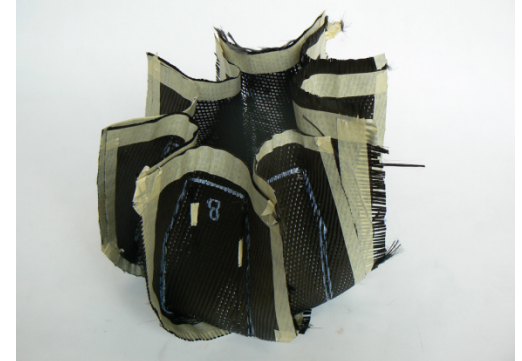
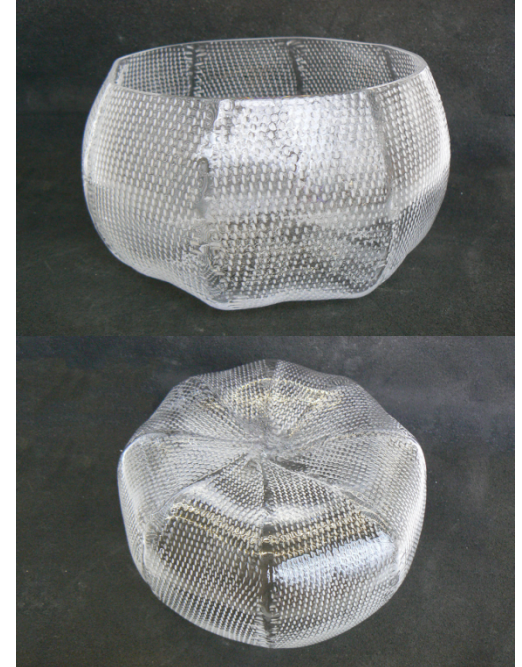


Design Optimization for Manufacturing (ii): Flattening Solution for Glass Production

► Molding by carbon fibers

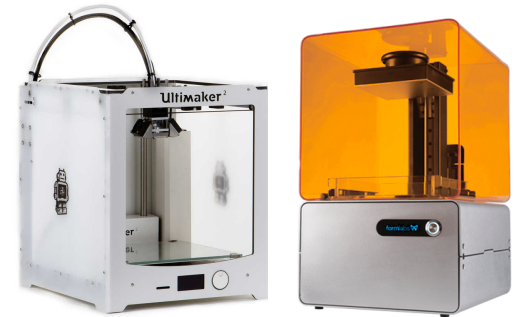


Design Optimization for Manufacturing (ii): Flattening Solution for Glass Production



3D Printing is NOT Completely Flexible

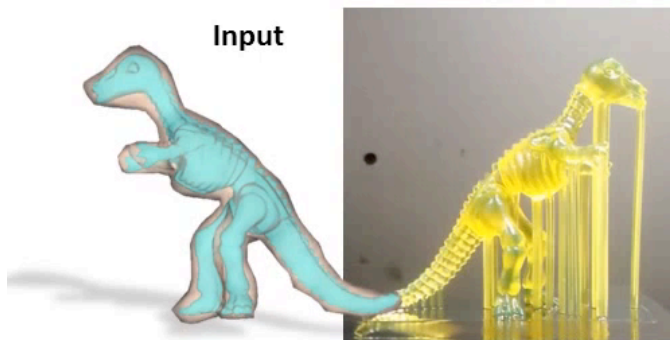
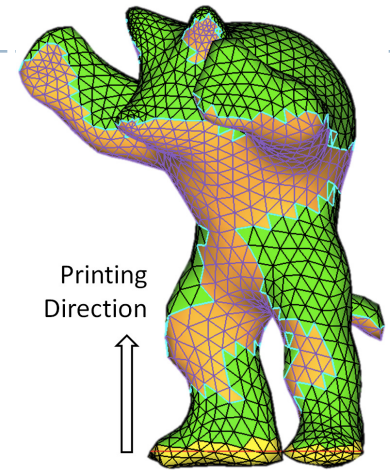
- ▶ Definition by ASTM for **Additive Manufacturing (AM)**
 - ▶ Process of joining materials to make objects from 3D model data, usually **layer upon layer**
- ▶ Good choice for personalized products
- ▶ **Overhangs** – **collapse** during fabrication
- ▶ Supporting structures – **hard to remove**



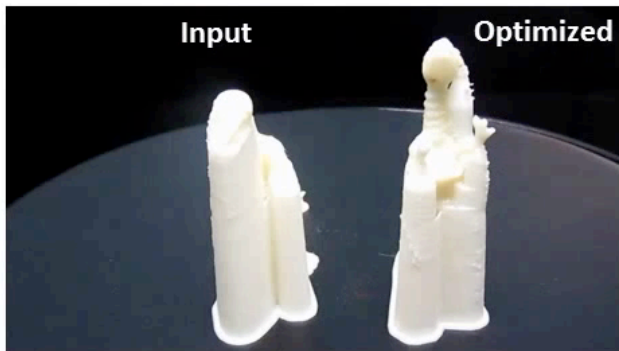
Design Optimization for Manufacturing (iii): Deformation to Reduce Overhang

Reduce the usage of **support** by **deformation**

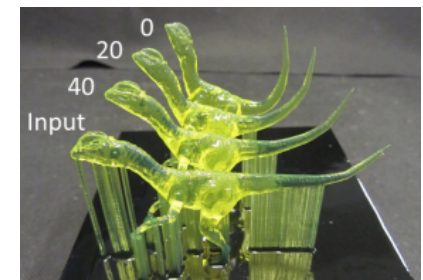
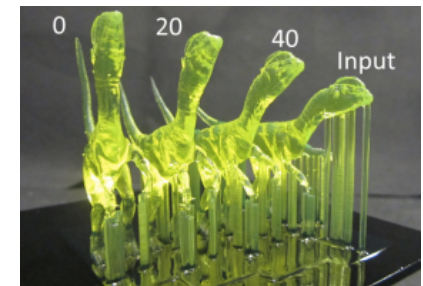
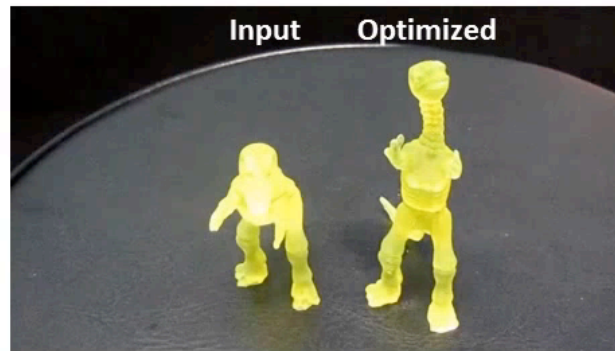
Dino



Fabricated by FDM

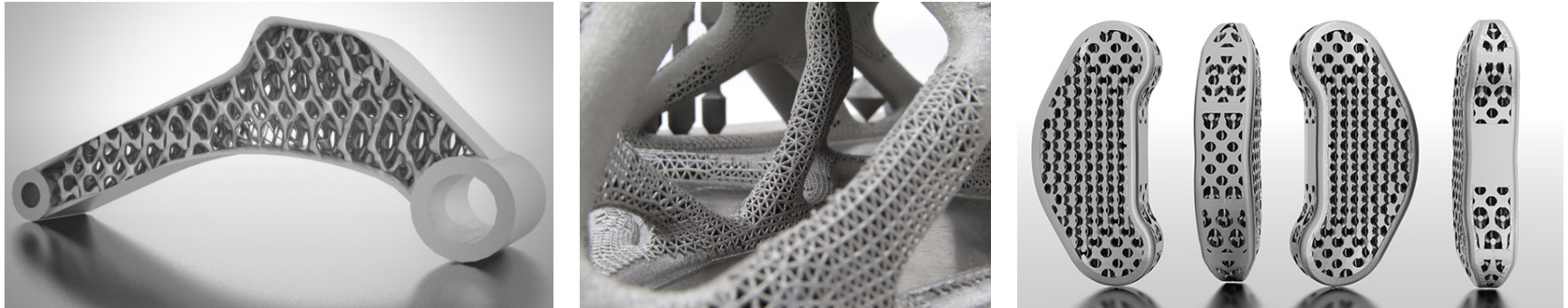


Fabricated by MIP-SLA



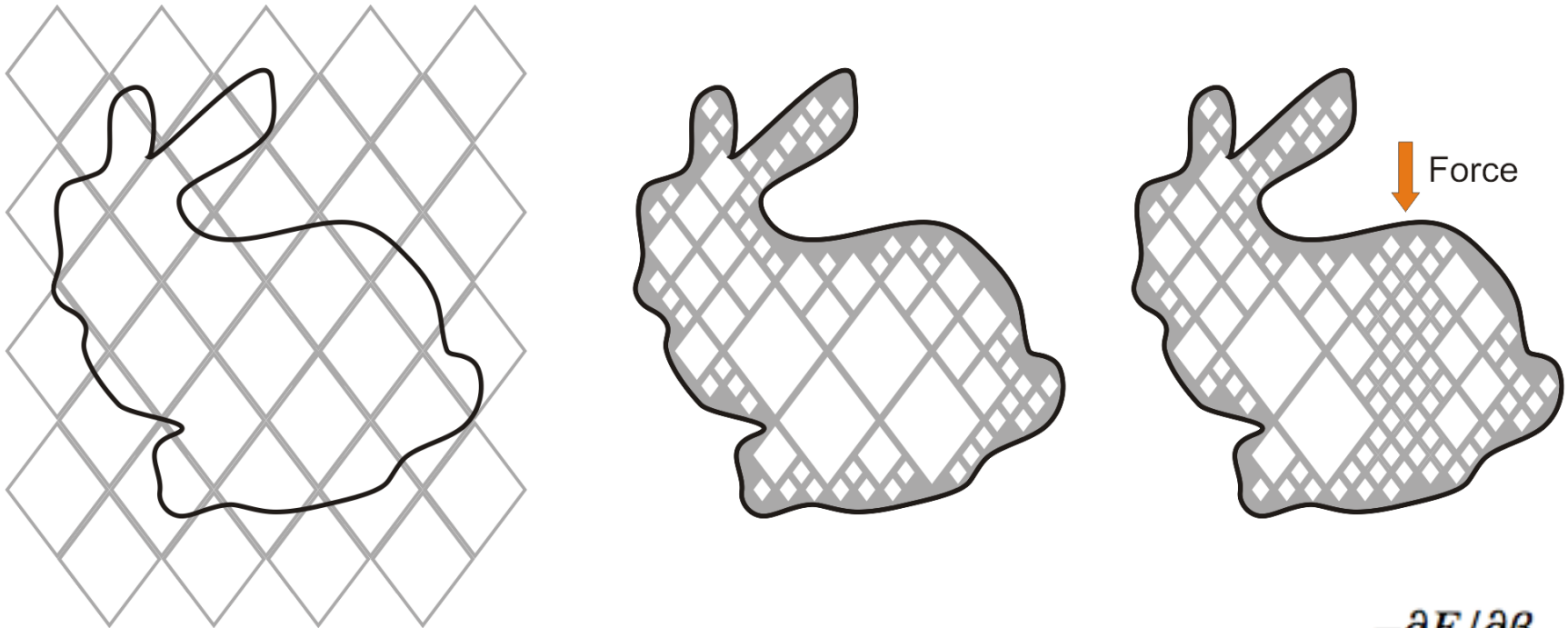
Fabrication-Aware Design Optimization: Infill Optimization for Mechanical Strength

- ▶ A lot of recent work in topology optimization



- ▶ **Problem: Manufacturability?** Especially for infill
- ▶ **Our solution:** by restricting topology optimization to generate structures in a manufacturability-ensured space
 - ▶ Use of grid **refinement** and **grid-to-cell** operators to efficiently perform the optimization
 - ▶ **Manufacturable** structure ensured by **rhombic** structures
 - ▶ Optimization of **mechanical stiffness** effectively and efficiently

Fabrication-Aware Design Optimization: Infill Optimization for Mechanical Strength

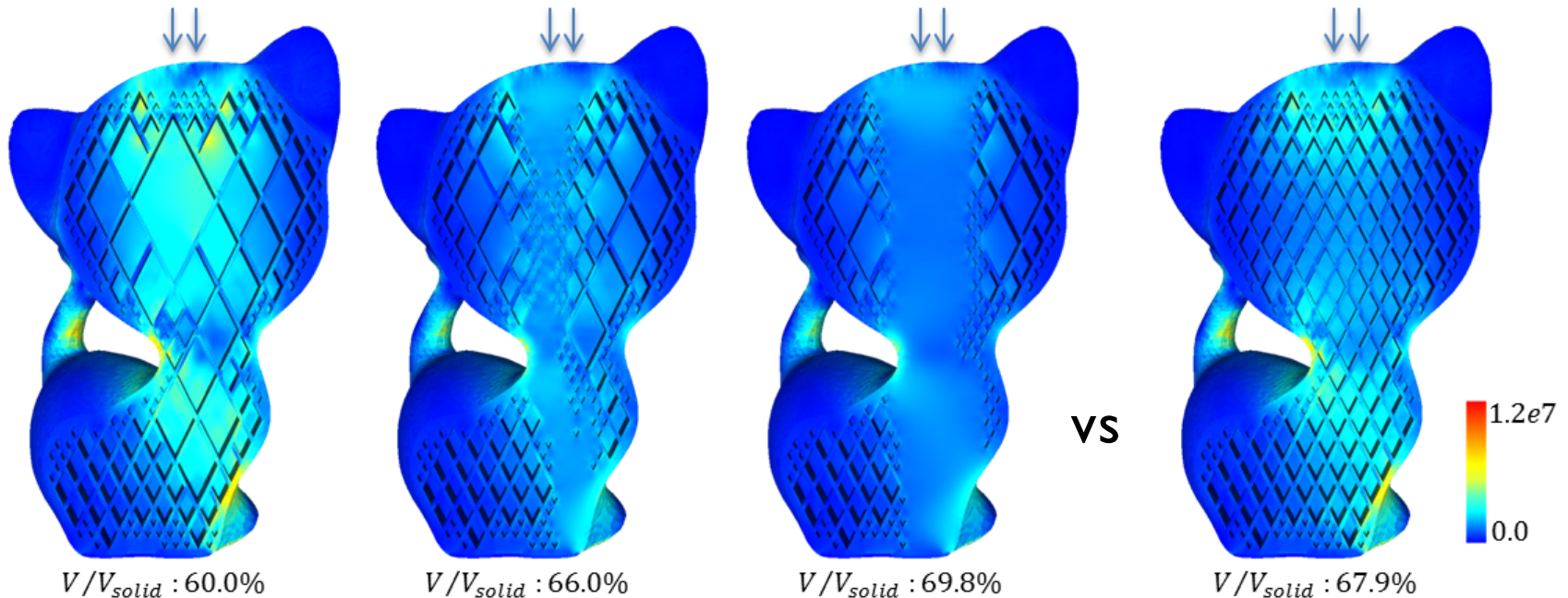
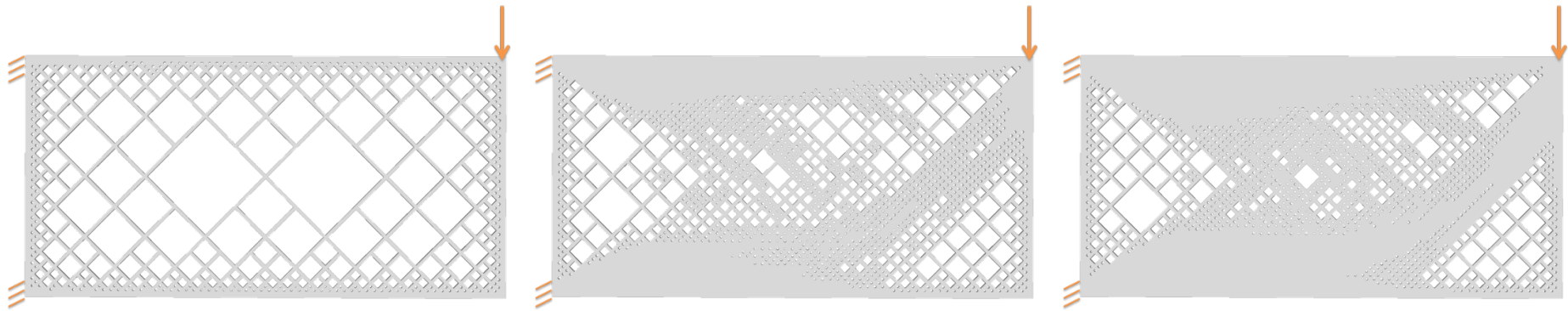


► An iterative process by sensitivity analysis:

$$G_c = \frac{-\partial E / \partial \beta_c}{\partial V / \partial \beta_c}$$

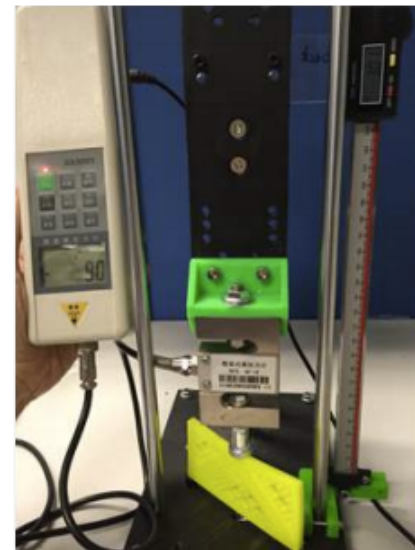
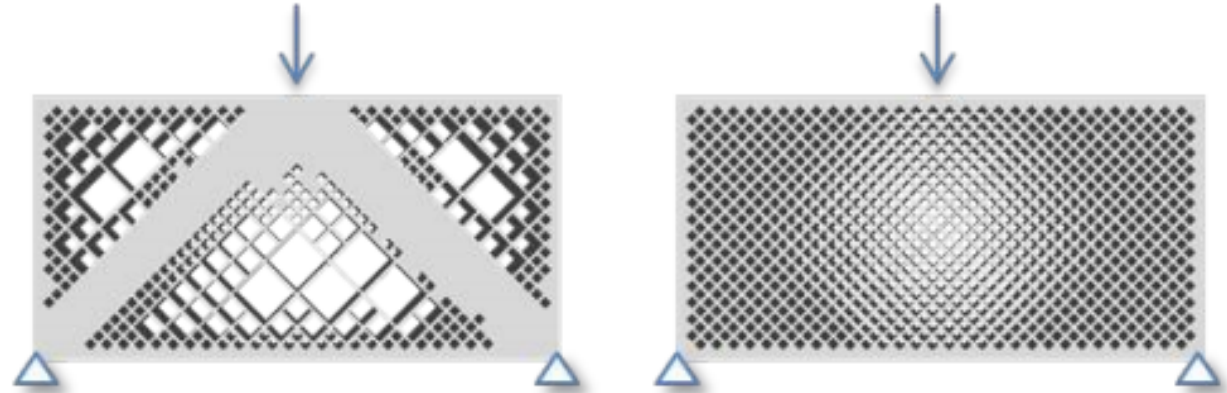
1. Finite Element Analysis of elasticity
2. Evaluate the sensitivity
3. Update the rhombic structure by subdividing selected cells

Fabrication-Aware Design Optimization: Infill Optimization for Mechanical Strength



Fabrication-Aware Design Optimization: Infill Optimization for Mechanical Strength

► Physical Tests (for comparison)

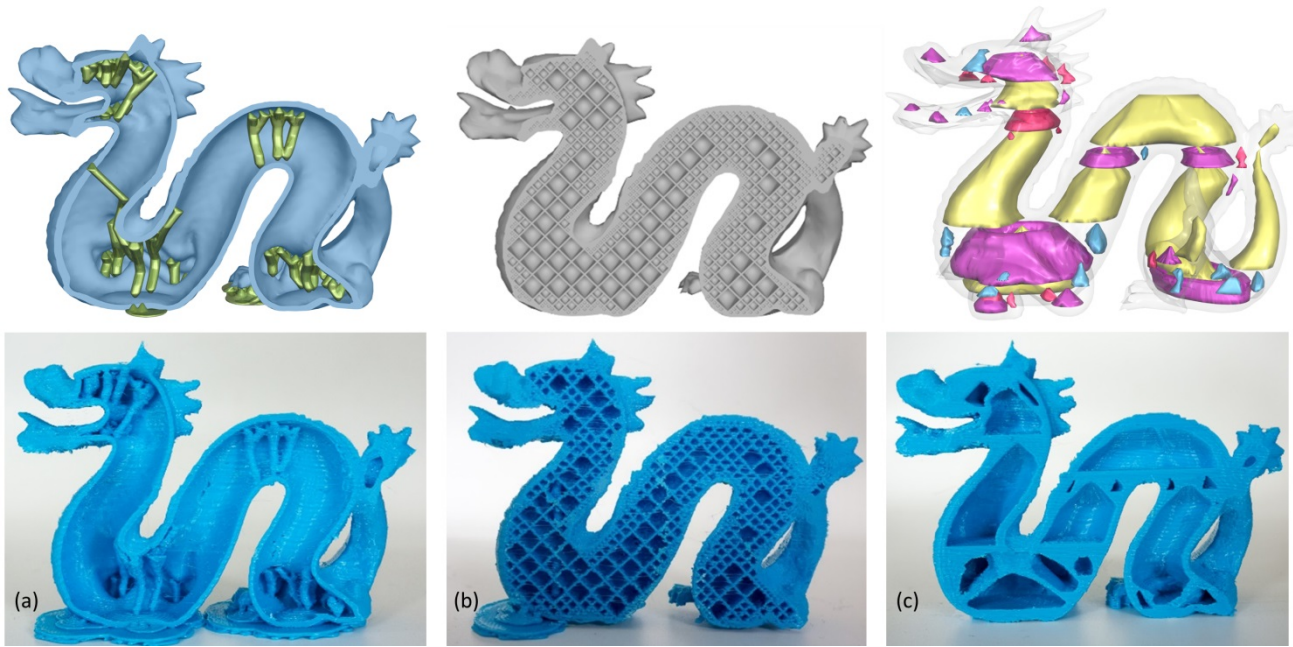


Applying the **same loading** (2.11 vs 4.08mm)

Under the **same displacement** (3mm)

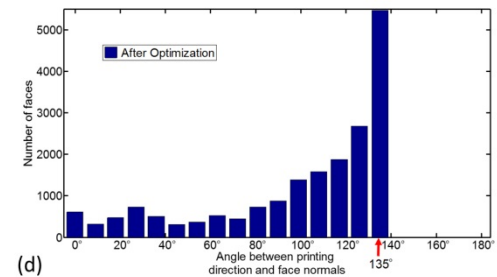
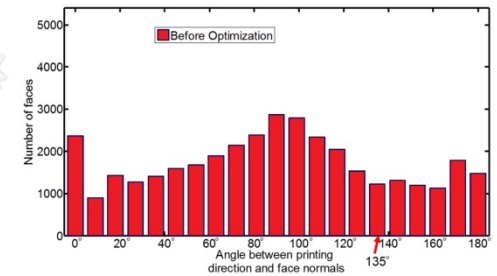
Fabrication-Aware Design Optimization (ii): Support-Free Hollowing

- ▶ To further enhance the sparsity of infill structures
 - ▶ Support-free hollowing **operator** based on **layered** formulation
 - ▶ A **repetitive hollowing strategy** to enlarge the solution space
 - ▶ Intrinsic solution for physics optimization

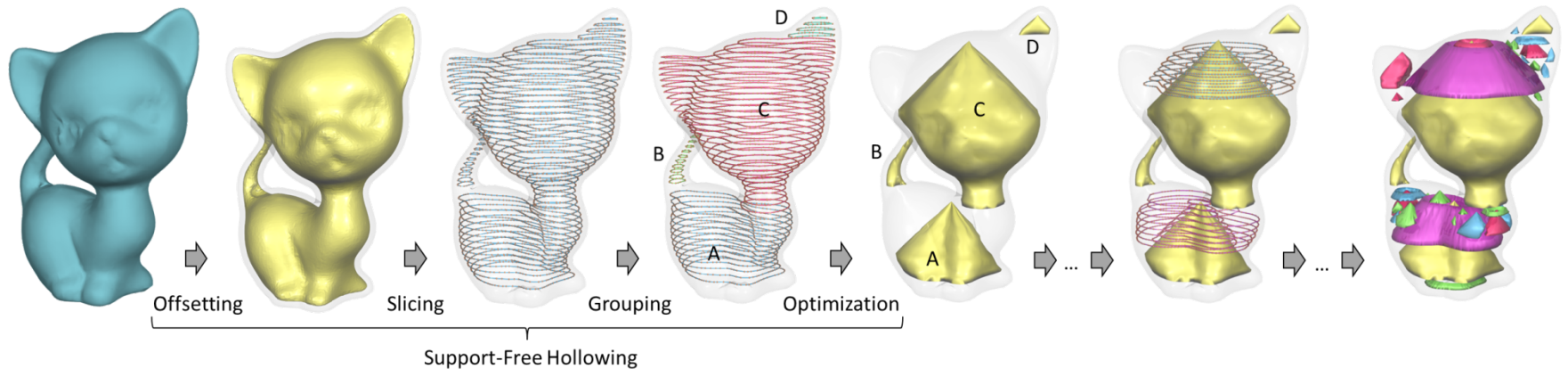


Reduce 38.0% Weight

Reduce 69.9% Weight

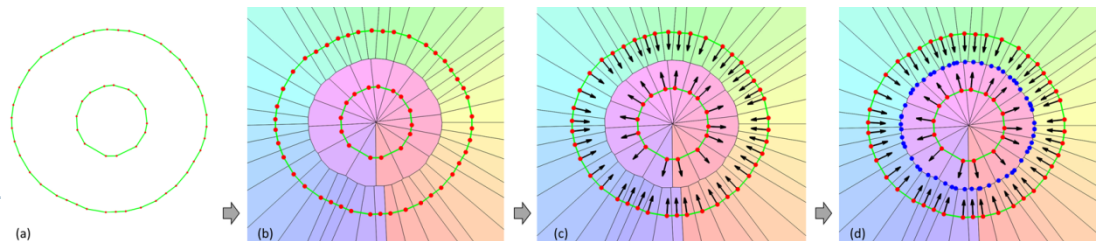


Fabrication-Aware Design Optimization (ii): Support-Free Hollowing

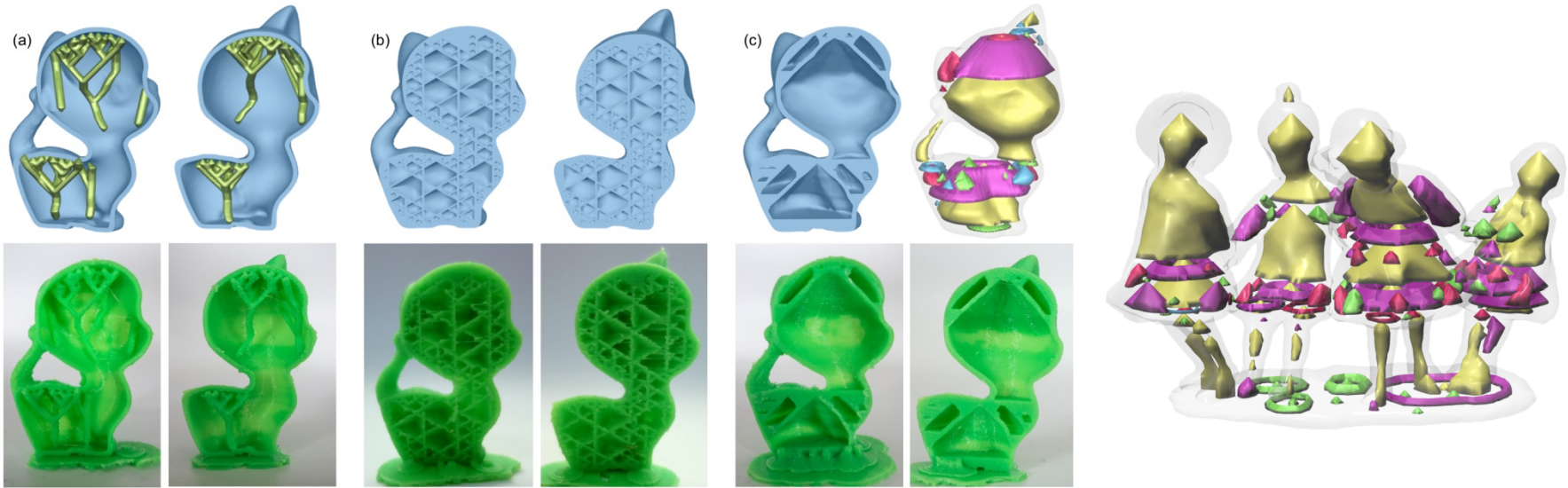


► Pipeline of iterative computation:

- Generate uniform offset surface as initial shape
- Slicing offset and **cluster** cross-sections into groups according to **topology** variation
- Planar Voronoi-Diagram governed collision-free optimization
- Repeat above steps

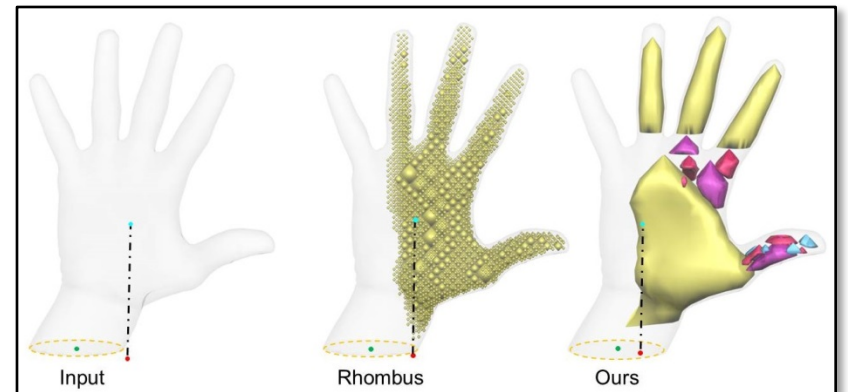
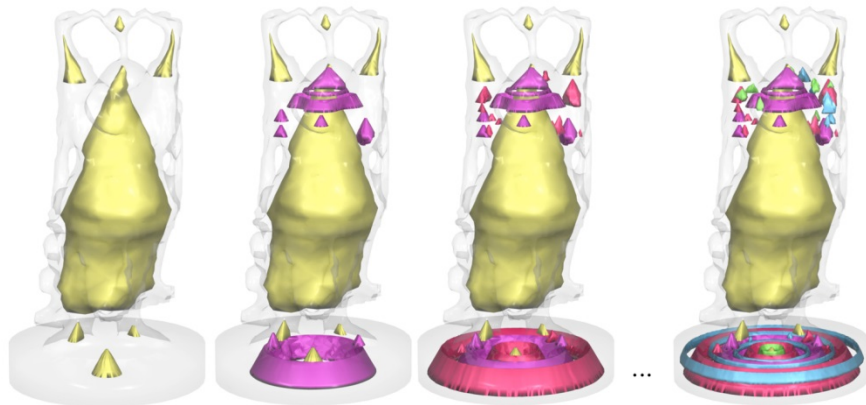


Fabrication-Aware Design Optimization (ii): Support-Free Hollowing



Reduce 45.5% Weight

Reduce 75.3% Weight



Optimization for Comfort: Thermal-Comfort Design of Personalized Casts



Thermal-Comfort Design of Personalized Casts

Xiaoting Zhang¹, Guoxin Fang², Chengkai Dai²,
Jouke Verlinden², Jun Wu², Emily Whiting¹, Charlie C.L. Wang²

¹Boston University

²TU Delft

ACM User Interface Software and Technology Symposium (UIST) 2017

Computational Design and Fabrication

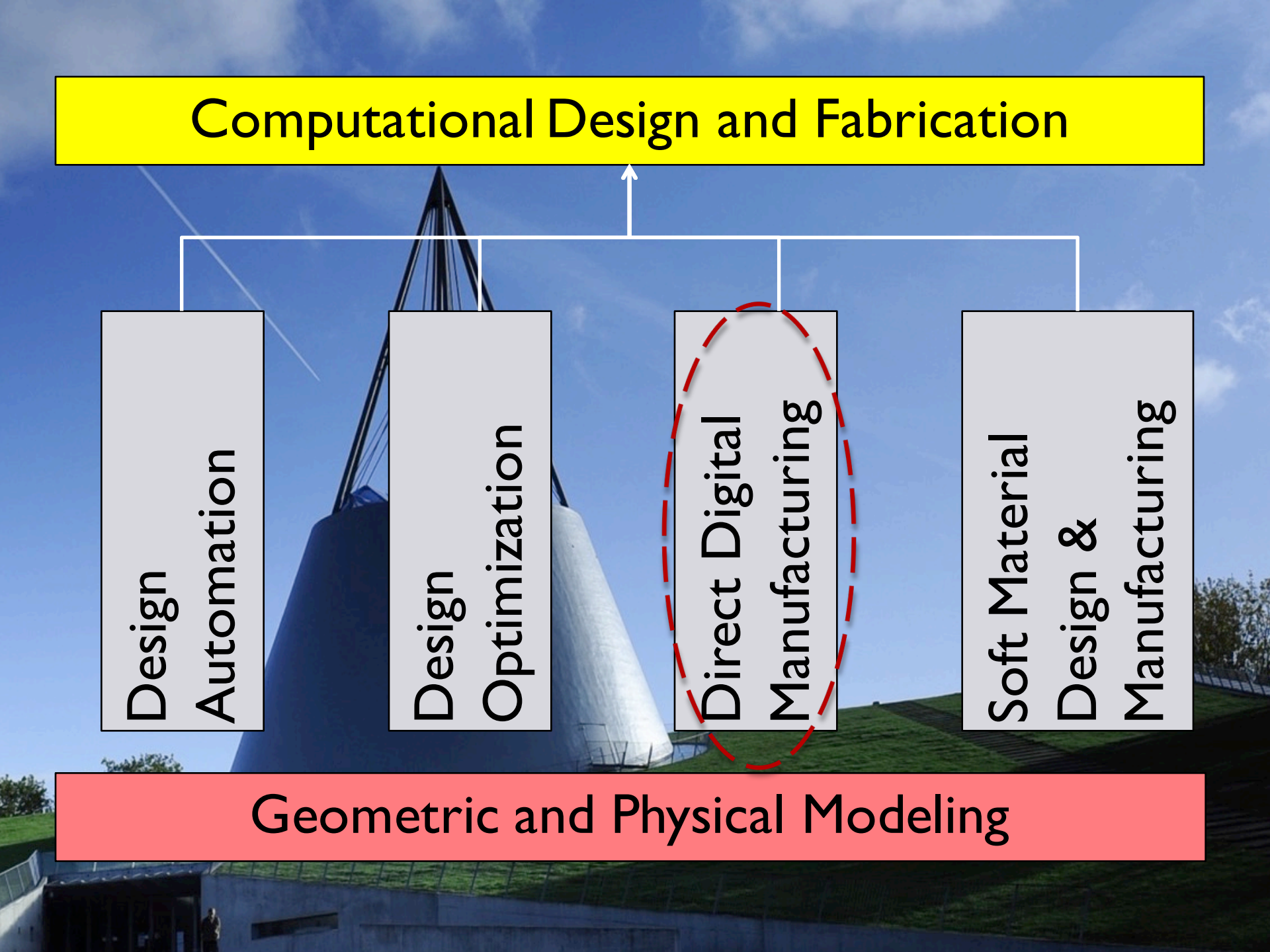
Design
Automation

Design
Optimization

Direct Digital
Manufacturing

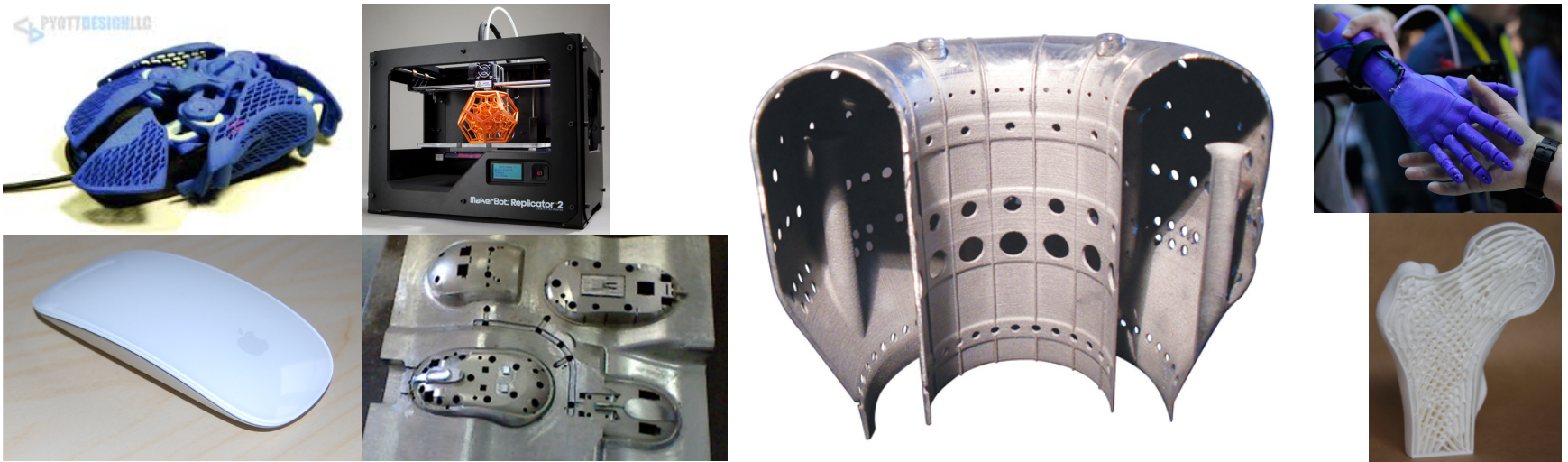
Soft Material
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Geometric and Physical Modeling

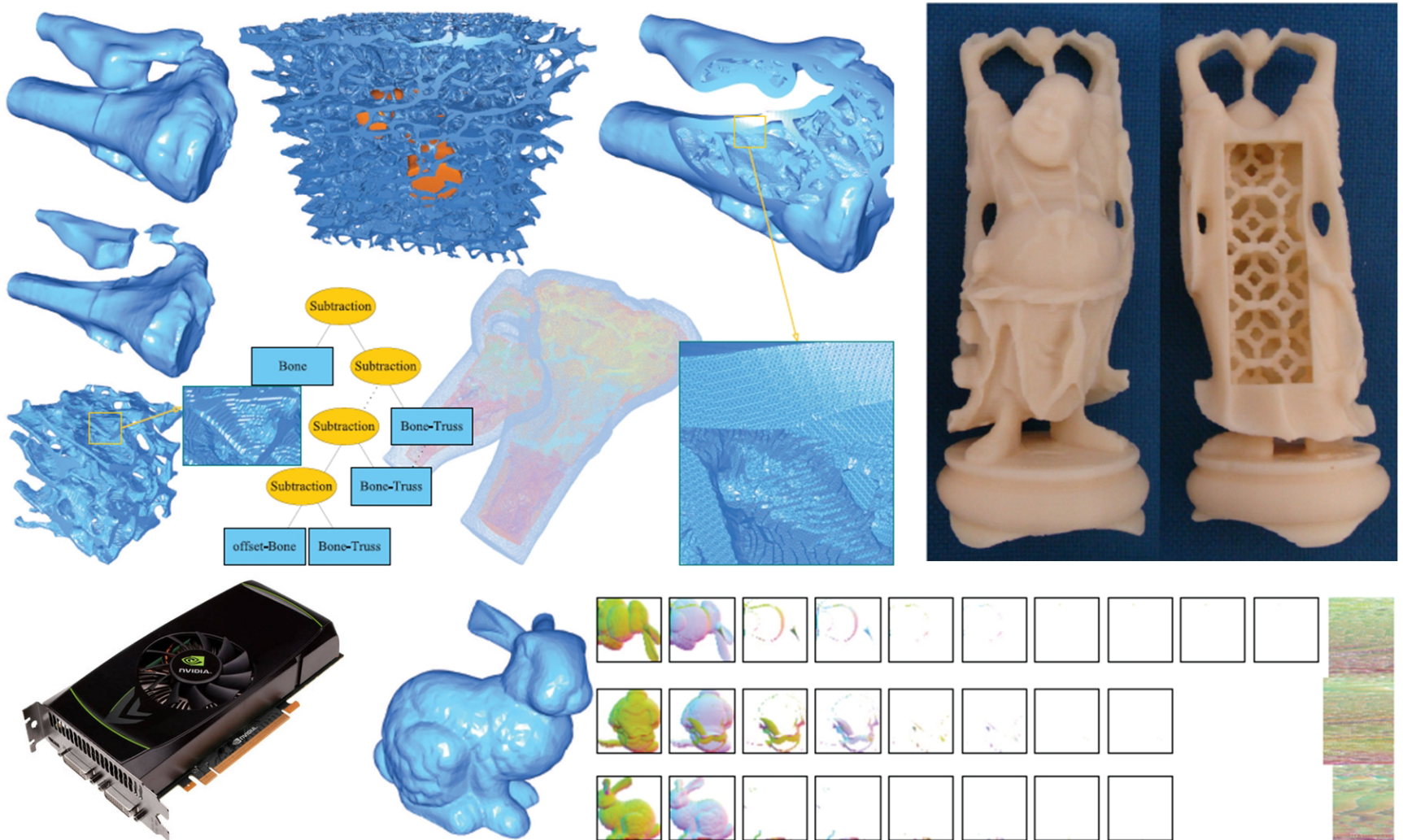


Direct Digital Manufacturing: Benefit and Challenge

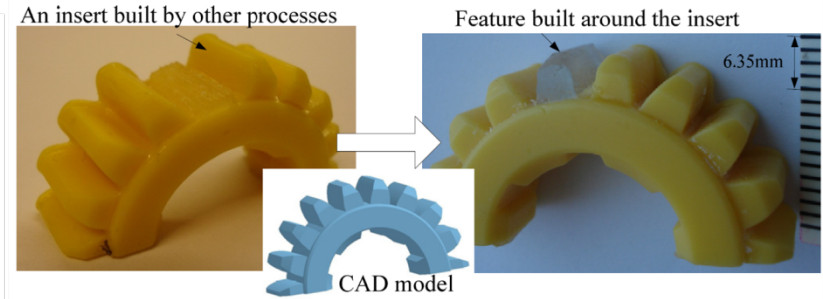
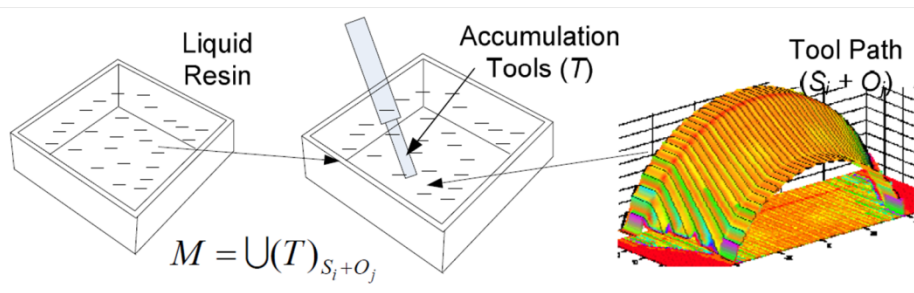
- ▶ Advantages: **flexibility** of fabricating complex shape and structure
- ▶ **Software** for **Computational Fabrication** becomes a **bottleneck** for new manufacturing methods
 - ▶ A **new modeling kernel** for complex shape and topology
 - ▶ **Control & optimization** for new manufacturing processes



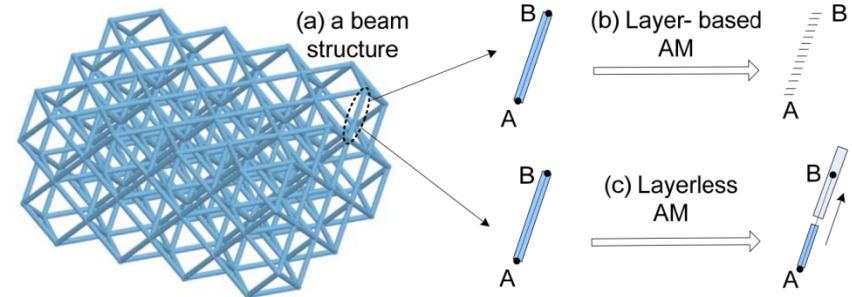
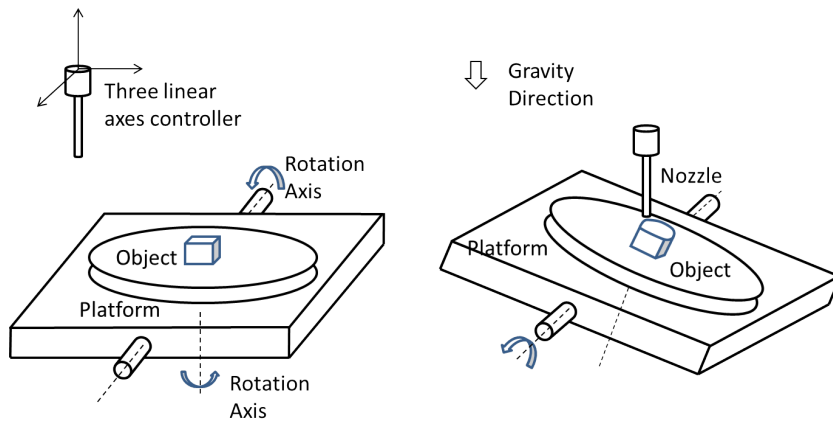
Geometric Kernel for 3D Printing: Highly Parallel Solid Modeling on GPUs



2.5D vs. 3D Printing: Simple or More DOF?

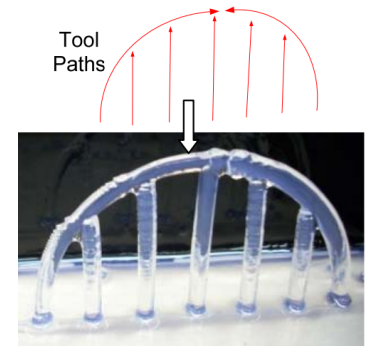


CNC accumulation for build-insert-around



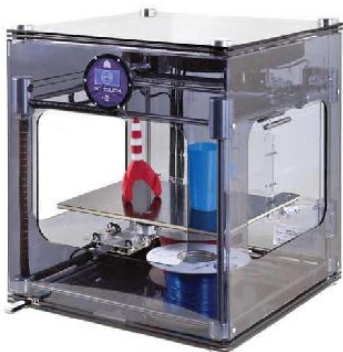
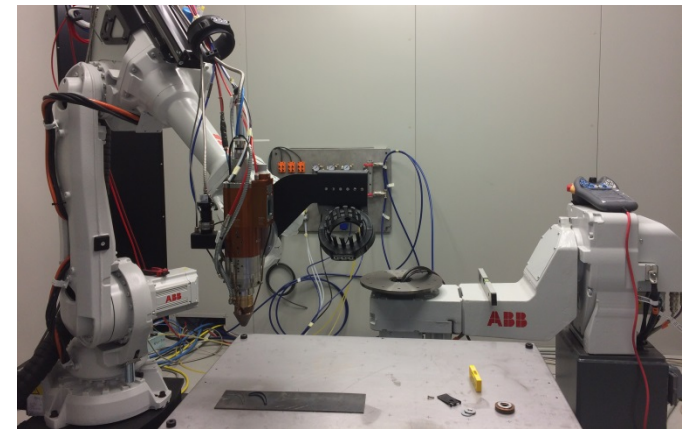
Develop a new **non-layered AM**

- Fused Deposition Modeling (FDM)
- Multi-axis motion introducing more flexibility

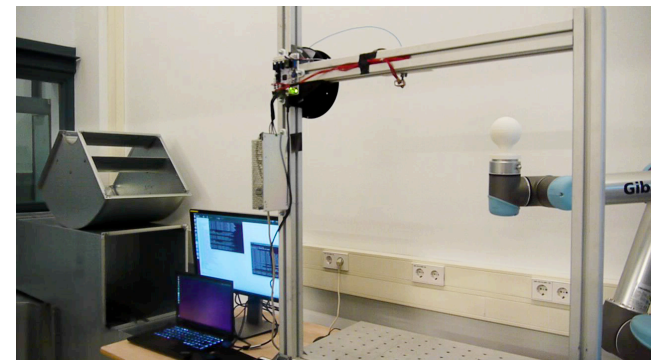
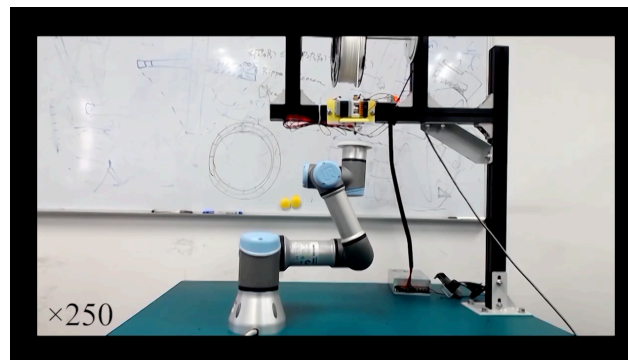


Robot-Assisted Multi-Axis AM

- ▶ Using robot arms as device for motion control in AM
- ▶ Collaborative operations on two arms – **More DoFs** to fabricate curved regions / layers
- ▶ Challenges:
 - ▶ Model **decomposition**
 - ▶ **Collision-free** tool path generation
 - ▶ Configurations in **joint-angle** space



VS



Decomposition by 3-half-half Axis AM

RoboFDM: A Robotic System for Support-Free Fabrication using FDM

**Chenming Wu^{1*}, Chengkai Dai^{2*}, Guoxin Fang²,
Yong-Jin Liu¹ and Charlie C.L. Wang^{2†}**

1. TNList, Department of Computer Science and Technology, Tsinghua University

2. Department of Design Engineering and TU Delft Robotics Institute, Delft University of Technology

*** Contributed equally † Corresponding Author**

Field-Governed 5DOF Volume Printing



GENERATIONS / VANCOUVER
12-16 AUGUST
SIGGRAPH2018

Support-Free Volume Printing by Multi-Axis Motion

Chengkai Dai¹ Charlie C.L. Wang^{1*} Chenming Wu² Sylvain Lefebvre³
Guoxin Fang¹ Yong-Jin Liu²

¹Delft University of Technology

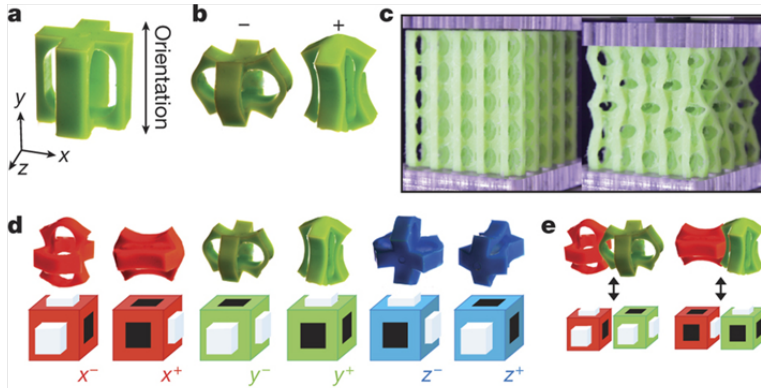
²Tsinghua University

³Inria

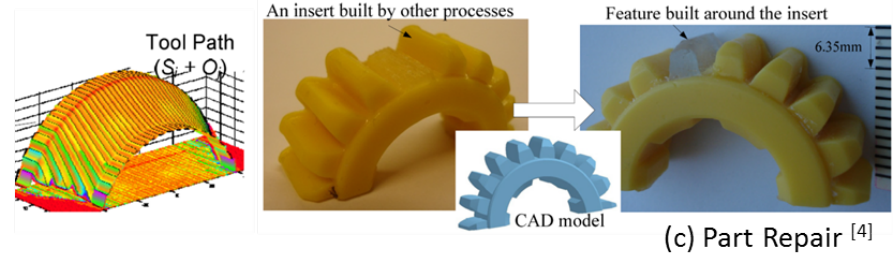
*Corresponding Author

Impact of Developing “Real” 3D Printing

- ▶ Accumulating materials in **space** but not **planar layers**



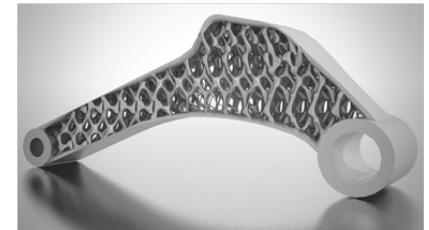
(a) Mechanical Meta-Materials [2] (Applied Physics)



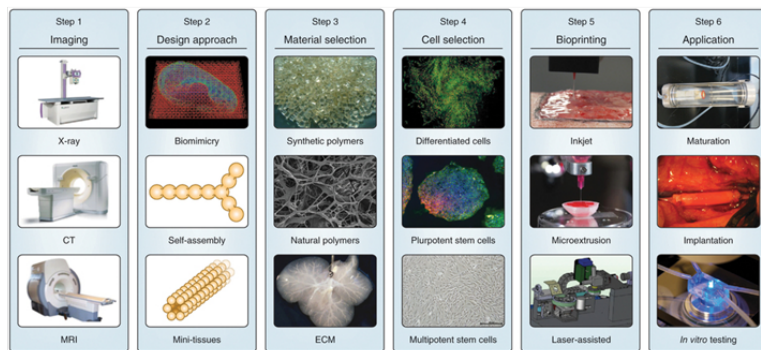
(c) Part Repair [4]

**Multi-Axis Additive Manufacturing
(Next Generation of 3D Printing)**

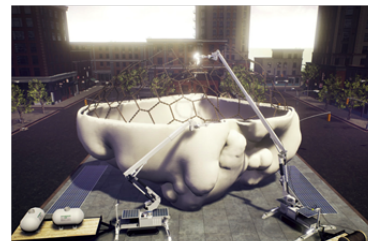
Geometric Computing



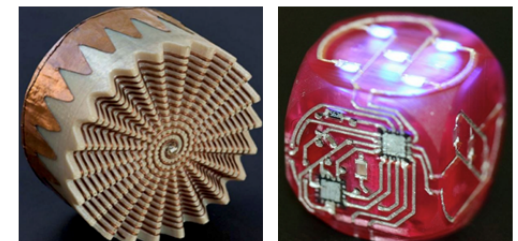
(d) Lightweight Structure
(www.autodesk.com)



(b) Tissue Engineering [3] (Life Science)



(e) Large-Scale Construction [6]



(f) Printing Electronics [8]

From 3D to 4D Printing

- ▶ 3D Printed **Self-Assembly** Structures
- ▶ How to **predict** the shape of fabricated model?
- ▶ Pattern Design / Process Optimization / New Triggers



Computational Design and Fabrication

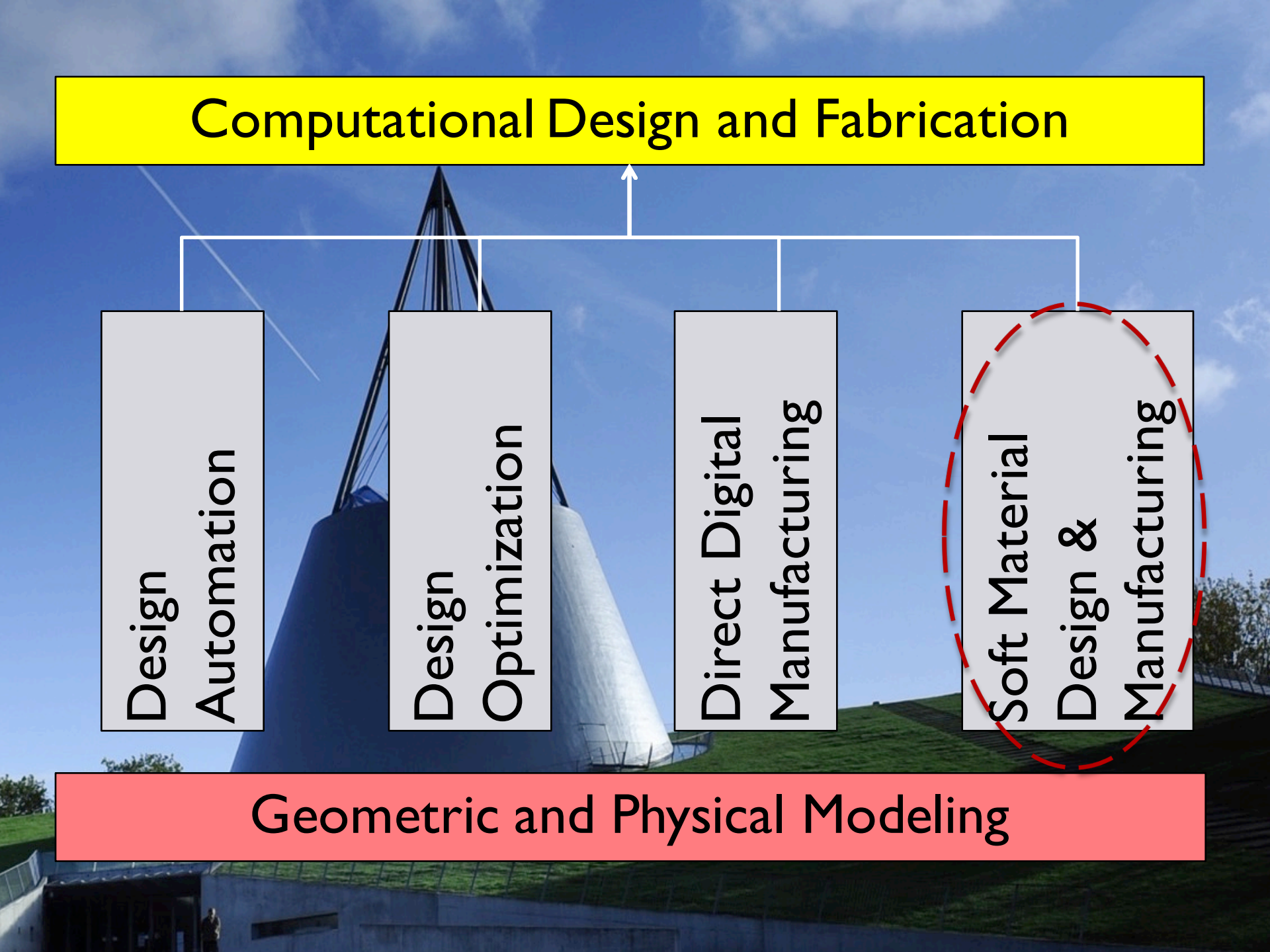
Design
Automation

Design
Optimization

Direct Digital
Manufacturing

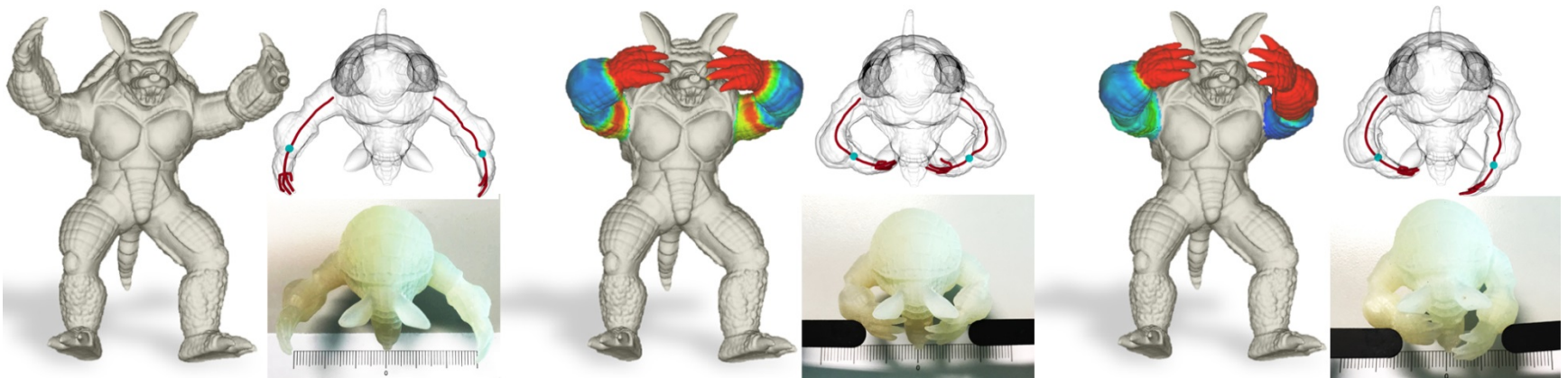
Soft Material
Design &
Manufacturing

Geometric and Physical Modeling



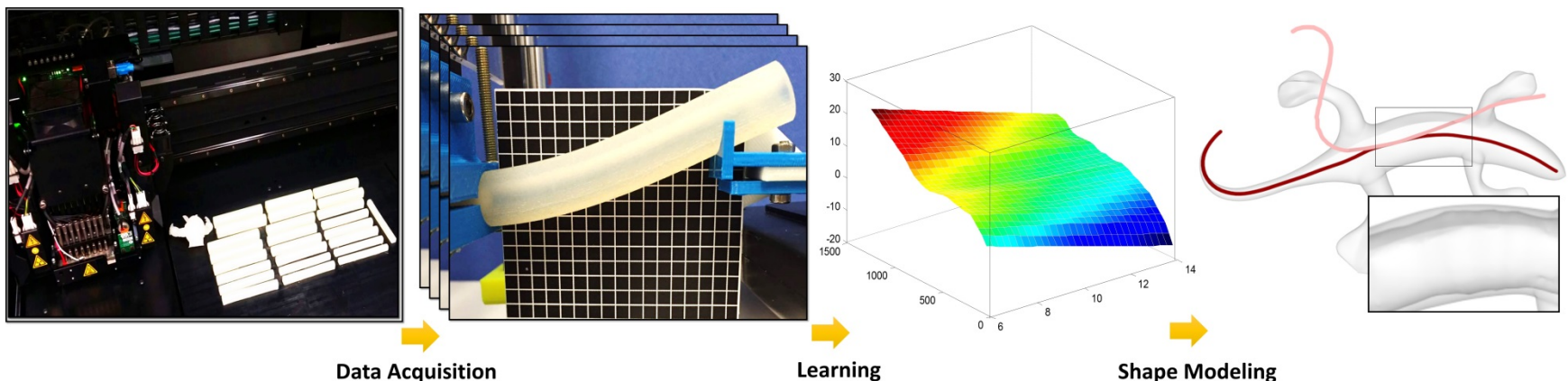
Deformation Behavior Design by Materials

- ▶ 3D printing with elastomers => Deformation Behavior?
- ▶ **Applications:** personalized products, toys and soft robotics
- ▶ Different external forces lead to five different loads:
 - ▶ *Bending, Compression, Shear, Tension and Torsion*
 - ▶ Bending gives the most **visible change** to shapes
- ▶ We provide – an interactive tool to design bending behavior
 - ▶ Non-uniform hollowing on **generalized cylindrical** shapes



Data-Driven Approach – Learning Function of Local Bending w.r.t. Shell Thickness

- ▶ **Variable** for bending behavior design: **thickness** of hollowing
- ▶ An interface to design the bending behavior – **ID skeleton**
- ▶ Offload time-consuming steps to the **phase of learning**
- ▶ **Challenge:**
 - ▶ To **match** the desired bending behavior
 - ▶ A **function** with **elasticity, thickness & dimension** of cross-section

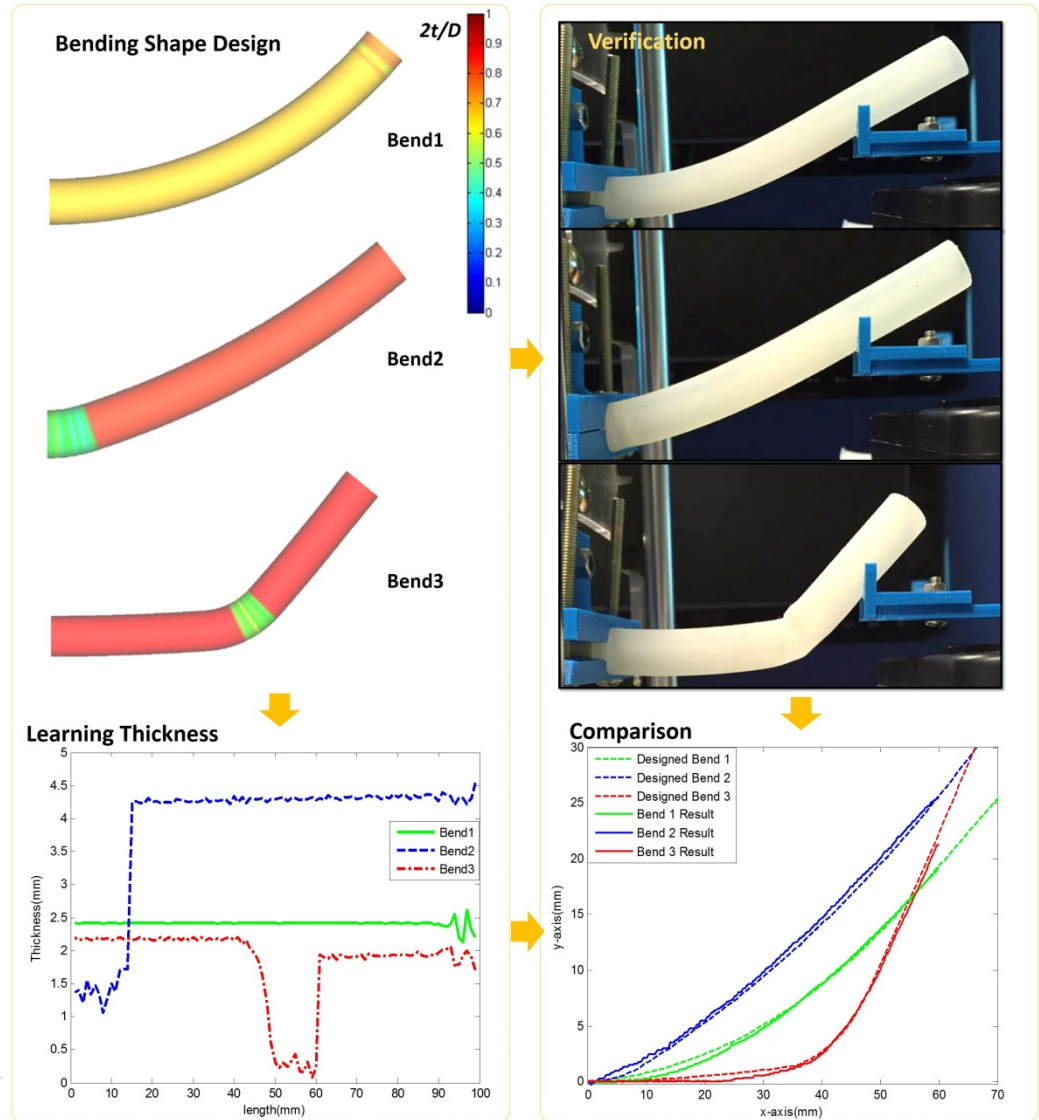


Result: Verification on Tubes

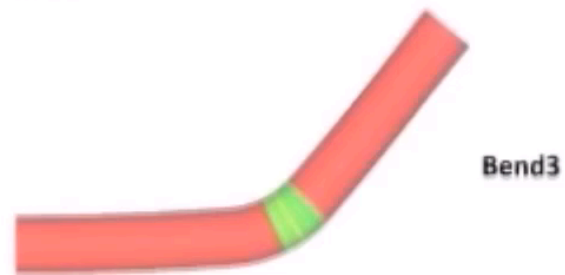
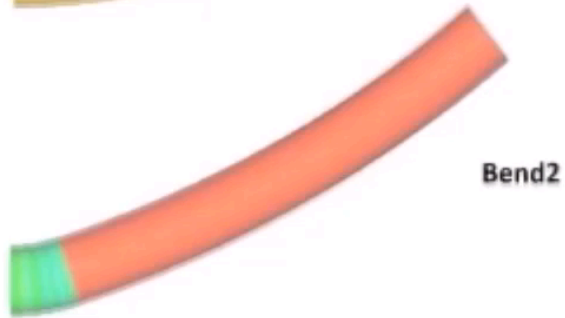
▶ Easy Interface



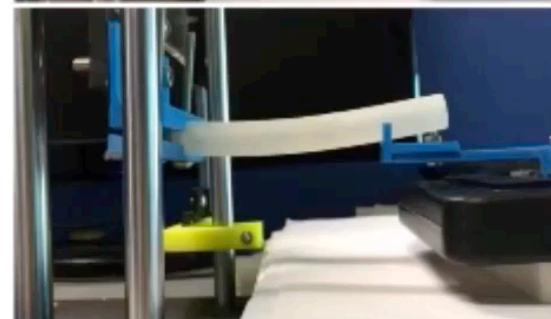
- ▶ Different behaviors
- ▶ Physical tests **match** designed behavior???

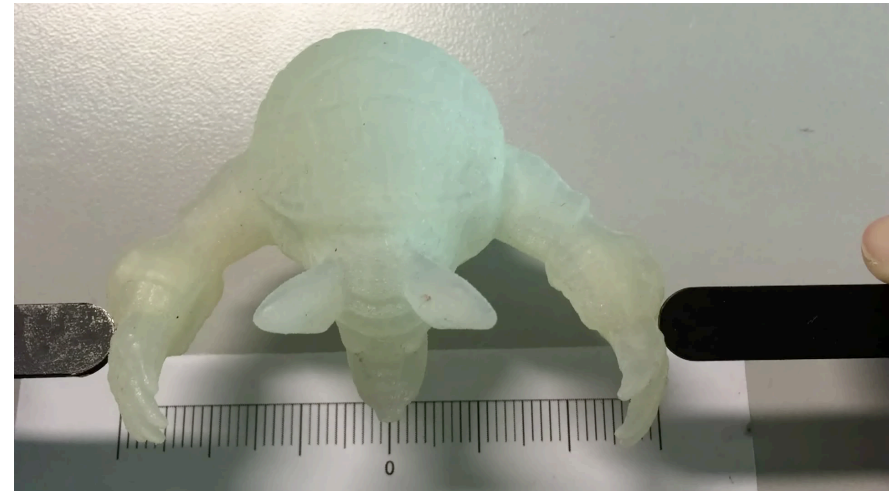
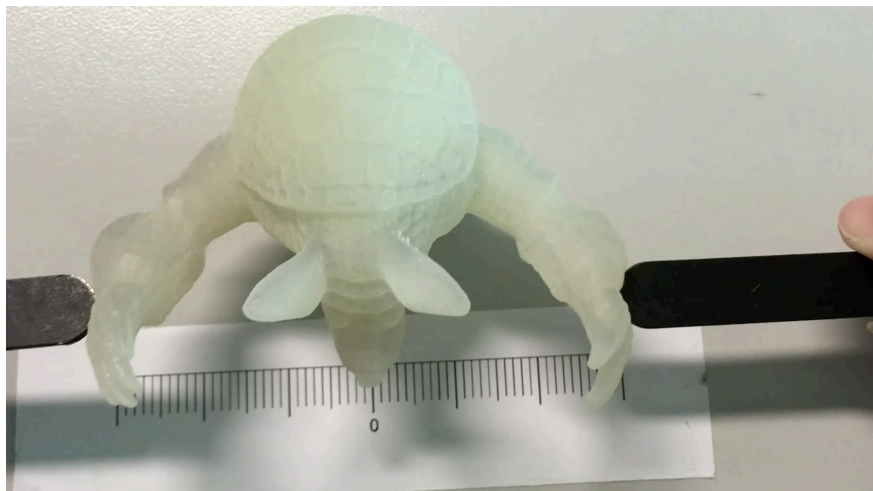
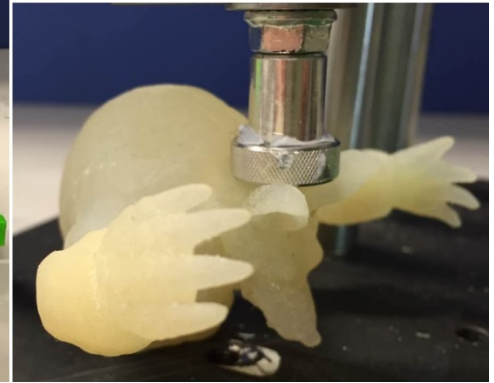
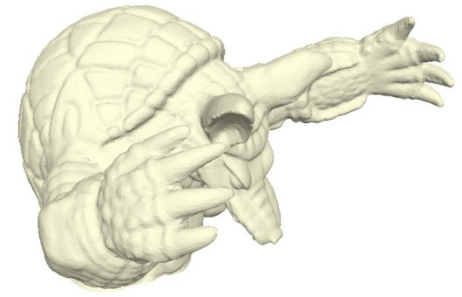
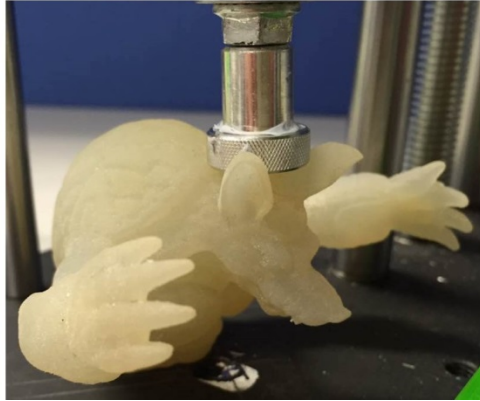
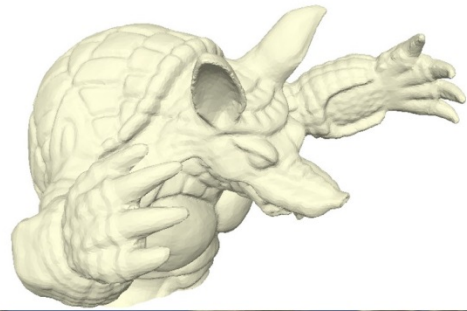


• Design



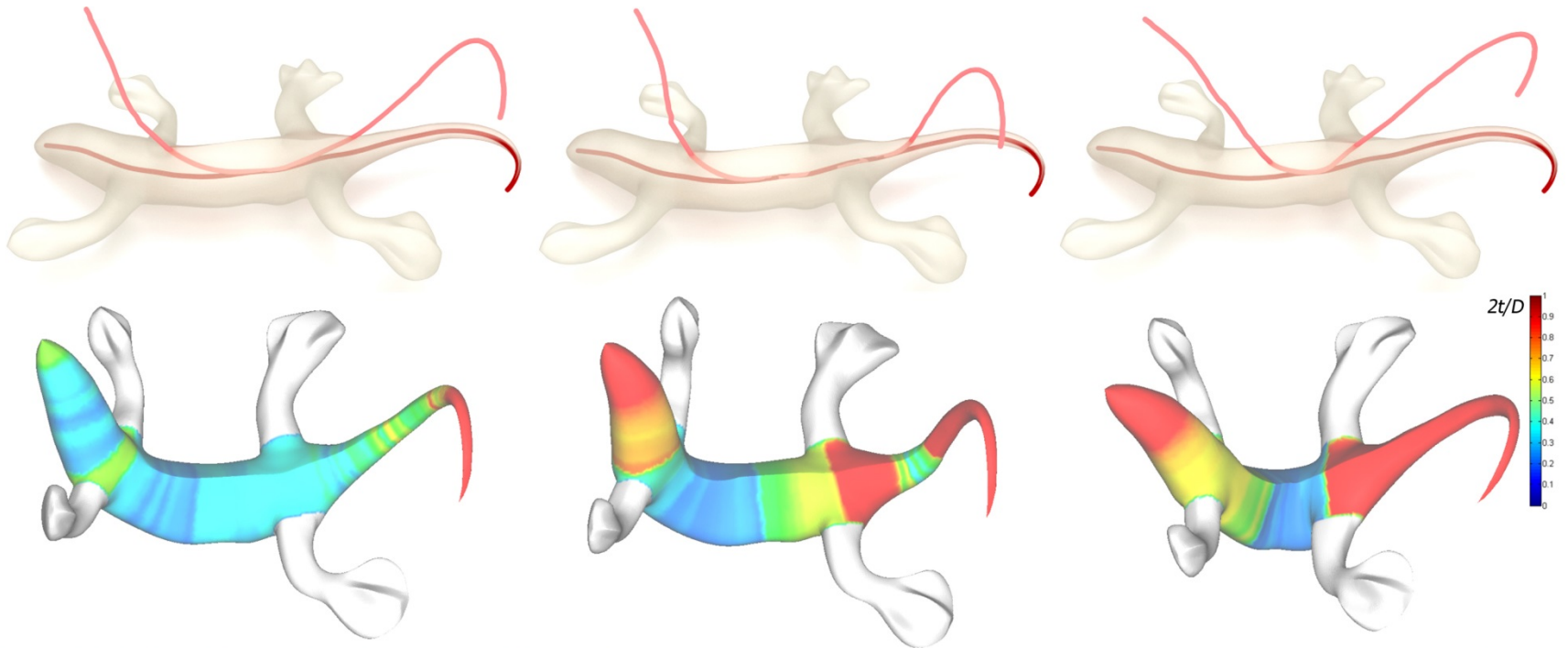
• Test



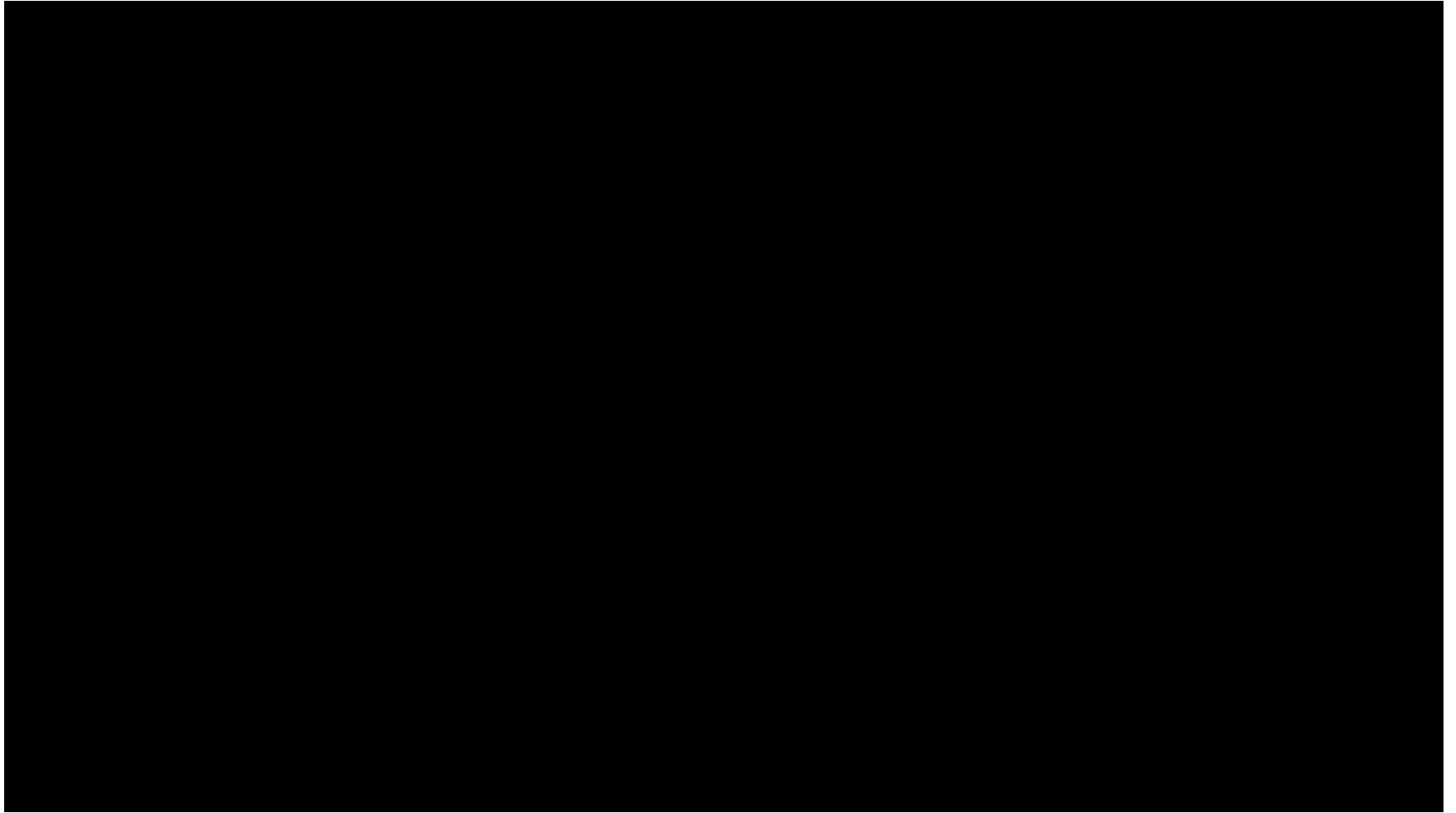


41 Xiaoting Zhang, Xinyi Le, Zhihao Wu, Emily Whiting, and Charlie C.L. Wang, "Data-driven bending elasticity design by shell thickness", *Computer Graphics Forum*, 2016.

Result: Models with Complex Shape

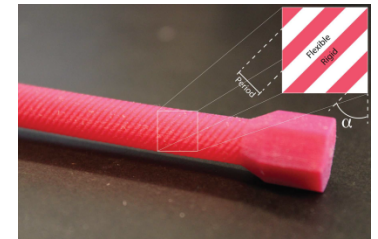


Direct Digital Manufacturing for Soft Robotics



Designing Deformation Behaviors for Soft Grippers

- ▶ **Soft robotics** application for better grippers
- ▶ Deformation behavior can also be influenced by the **material distribution** (Multi-Material Printing)



Parameterize
Deformation
Behavior
under:

- Bending
- Twisting
- Stretching

Behavior Design by Multi-Material AM

Designing Coupled Behavior of 3D-Printed Heterogeneous Materials for Soft Robotics

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Sensing of Bending Deformation

Color-Based Sensing of Bending Deformation on Soft Robots

Scharff, R.B., Doornbusch, R.M., Klootwijk X.L., Doshi A.A.,
Doubrovski, E.L., Wu, J., Geraedts, J.M., Wang, C.C.*

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