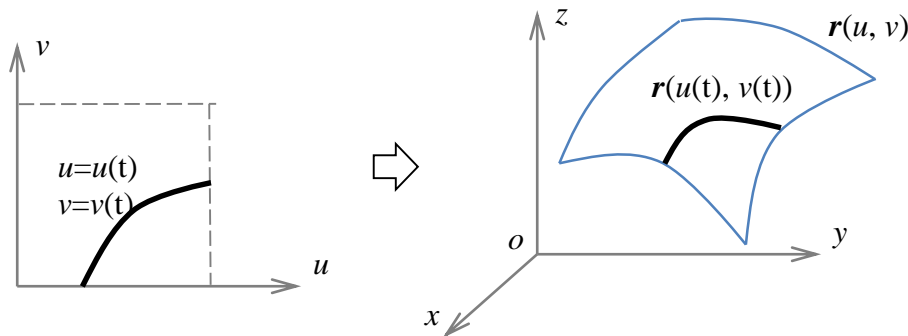


L8 – Differential Geometry of Surfaces

- We will discuss intrinsic properties of surfaces independent its parameterization
- Topics to be covered including:
 - Tangent plane and surface normal
 - First fundamental form I (metric)
 - Second fundamental form II (curvature)
 - Principal curvatures
 - Gaussian and mean curvatures
 - Euler's theorem

Tangent Plane and Surface Normal

- Consider a curve $u=u(t)$ $v=v(t)$ in the parametric domain of a parametric surface $\mathbf{r}=\mathbf{r}(u, v)$, then $\mathbf{r}=\mathbf{r}(t)=\mathbf{r}(u(t), v(t))$ is a parametric curve lying on the surface \mathbf{r} .

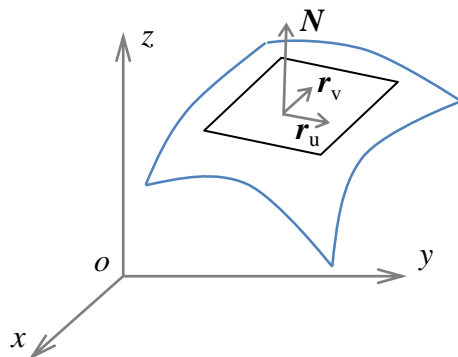


Using the chain rule on

$$\mathbf{r}(t)=\mathbf{r}(u(t), v(t))$$

$$\Rightarrow \dot{\mathbf{r}}(t) = \mathbf{r}_u \dot{u} + \mathbf{r}_v \dot{v}$$

- The tangent plane at point \mathbf{p} can be considered as a union of the tangent vectors of the form in above equation for all $\mathbf{r}(t)$ (i.e., many curves) passing through \mathbf{p} .



$$\mathbf{N} = \frac{\mathbf{r}_u \times \mathbf{r}_v}{\|\mathbf{r}_u \times \mathbf{r}_v\|}$$

Tangent Plane and Surface Normal (cont.)

- The equation of the tangent plane at $\mathbf{r}(u_p, v_p)$ is

$$(\mathbf{p} - \mathbf{r}(u_p, v_p)) \cdot \mathbf{N}(u_p, v_p) = 0$$

- **Definition:** A **regular** (ordinary) point p on a parametric surface is defined as a point where $\mathbf{r}_u \times \mathbf{r}_v \neq 0$. A point with $\mathbf{r}_u \times \mathbf{r}_v = 0$ is called a **singular** point.

- **Implicit** surface $f(x,y,z)=0$, the unit normal vector is given by

$$\mathbf{N} = \frac{\nabla f}{\|\nabla f\|}$$

First Fundamental Form I (Metric)

- If we define the parametric curve by a curve $u=u(t)$ $v=v(t)$ on a parametric surface $\mathbf{r}=\mathbf{r}(u,v)$

$$\begin{aligned} ds &= \left\| \frac{d\mathbf{r}}{dt} \right\| dt = \left\| \mathbf{r}_u \frac{du}{dt} + \mathbf{r}_v \frac{dv}{dt} \right\| dt \\ &= \sqrt{(\mathbf{r}_u \dot{u} + \mathbf{r}_v \dot{v}) \cdot (\mathbf{r}_u \dot{u} + \mathbf{r}_v \dot{v})} dt \\ &= \sqrt{E du^2 + 2F du dv + G dv^2} \quad (\because \dot{u} = \frac{du}{dt}, \dot{v} = \frac{dv}{dt}) \end{aligned}$$

where

$$E = \mathbf{r}_u \cdot \mathbf{r}_u, \quad F = \mathbf{r}_u \cdot \mathbf{r}_v, \quad G = \mathbf{r}_v \cdot \mathbf{r}_v$$

- E, F, G are call the **first fundamental form coefficients** and play important role in many intrinsic properties of a surface

First Fundamental Form I (cont.)

- **Definition:** The first fundamental form is defined as

$$I = (ds)^2 = d\mathbf{r} \cdot d\mathbf{r} = Edu^2 + 2Fdudv + Gdv^2$$

which can also be rewritten as

$$I = \frac{1}{E} (Edu + Fdv)^2 + \frac{EG - F^2}{E} (dv)^2$$

$$\begin{aligned} &(a \times b) \cdot (c \times d) \\ &= (a \cdot c)(b \cdot d) - (a \cdot d)(b \cdot c) \end{aligned}$$

- We can then have

$$E = \mathbf{r}_u \cdot \mathbf{r}_u > 0$$

$$(\mathbf{r}_u \times \mathbf{r}_v)^2 = (\mathbf{r}_u \times \mathbf{r}_v) \cdot (\mathbf{r}_u \times \mathbf{r}_v)$$

$$= (\mathbf{r}_u \cdot \mathbf{r}_u)(\mathbf{r}_v \cdot \mathbf{r}_v) - (\mathbf{r}_u \cdot \mathbf{r}_v)^2 = EG - F^2 > 0$$

- Conclusion: we know that I is positive definite, provided that the surface is **regular** (since $I \geq 0$ and $I = 0$ if and only if $du=0$ and $dv=0$ at the same time)

Example I: Let's compute the arc length of a curve $u = t, v = t$ for $0 \leq t \leq 1$ on a hyperbolic paraboloid $\mathbf{r}(u, v) = (u, v, uv)^T$ where $0 \leq u, v \leq 1$.

Solution: $\mathbf{r}_u = (1, 0, v)^T, \mathbf{r}_v = (0, 1, u)^T$

$E = \mathbf{r}_u \cdot \mathbf{r}_u = 1 + v^2, G = \mathbf{r}_v \cdot \mathbf{r}_v = 1 + u^2, F = \mathbf{r}_u \cdot \mathbf{r}_v = uv.$
and along the curve the first fundamental form coefficients are

$$E = 1 + t^2, G = 1 + t^2, F = t^2.$$

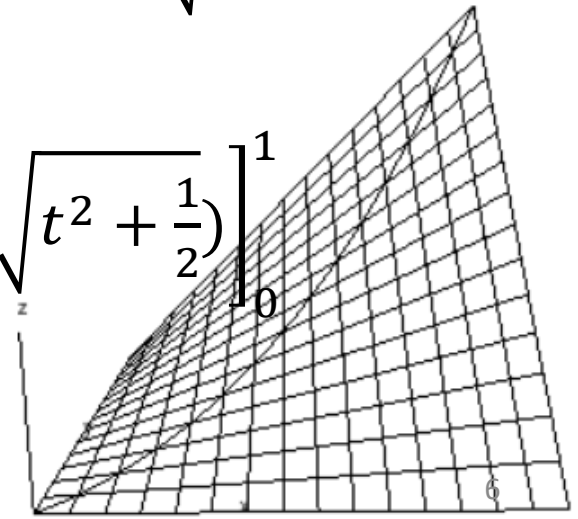
Thus

$$ds = \sqrt{E\dot{u}^2 + 2F\dot{u}\dot{v} + G\dot{v}^2} dt = \sqrt{2 + 4t^2} dt = 2\sqrt{t^2 + \frac{1}{2}} dt$$

The arc length

$$s = \int_0^1 2\sqrt{t^2 + \frac{1}{2}} dt = \left[t\sqrt{t^2 + \frac{1}{2}} + \frac{1}{2} \log\left(t + \sqrt{t^2 + \frac{1}{2}}\right) \right]_0^1$$

$$= \sqrt{\frac{3}{2}} + \frac{1}{2} \log(\sqrt{2} + \sqrt{3})$$



First Fundamental Form I (Angle)

- The angle between two curves on a parametric surface

$$\mathbf{r}_1 = \mathbf{r}(u_1(t), v_1(t)), \mathbf{r}_2 = \mathbf{r}(u_2(t), v_2(t))$$

can be evaluated by taking the **inner product** of their tangent vectors.

$$\begin{aligned} \cos \omega &= \frac{d\mathbf{r}_1 \cdot d\mathbf{r}_2}{\|d\mathbf{r}_1\| \|d\mathbf{r}_2\|} \\ &= \frac{Edu_1 du_2 + F(du_1 dv_2 + dv_1 du_2) + Gdv_1 dv_2}{\sqrt{Edu_1^2 + 2Fdu_1 dv_1 + Gdv_1^2} \sqrt{Edu_2^2 + 2Fdu_2 dv_2 + Gdv_2^2}} \end{aligned}$$

- As a result, the orthogonality condition for $\dot{\mathbf{r}}_1$ and $\dot{\mathbf{r}}_2$ is

$$Edu_1 du_2 + F(du_1 dv_2 + dv_1 du_2) + Gdv_1 dv_2 = 0$$

- In particular, the angle of two iso-parametric curves is

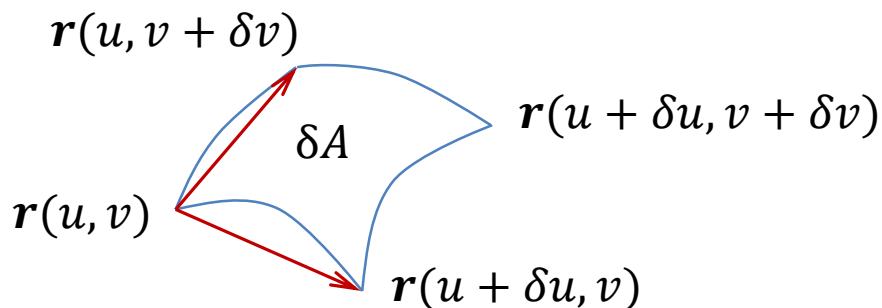
$$\cos \omega = \frac{\mathbf{r}_u \cdot \mathbf{r}_v}{\|\mathbf{r}_u\| \|\mathbf{r}_v\|} = \frac{\mathbf{r}_u \cdot \mathbf{r}_v}{\sqrt{\mathbf{r}_u \cdot \mathbf{r}_u} \sqrt{\mathbf{r}_v \cdot \mathbf{r}_v}} = \frac{F}{\sqrt{EG}}$$

Thus, the iso-parametric curves are **orthogonal** if $F \equiv 0$.

First Fundamental Form I (Area)

- The area of a small parallelogram with 4 vertices

$$\mathbf{r}(u, v), \mathbf{r}(u + \delta u, v), \mathbf{r}(u, v + \delta v), \mathbf{r}(u + \delta u, v + \delta v)$$



is approximated by

$$\begin{aligned} \delta A &= \|\mathbf{r}_u \delta u \times \mathbf{r}_v \delta v\| = \sqrt{EG - F^2} \delta u \delta v \\ (\because (\mathbf{r}_u \times \mathbf{r}_v)^2 &= (\mathbf{r}_u \cdot \mathbf{r}_u)(\mathbf{r}_v \cdot \mathbf{r}_v) - (\mathbf{r}_u \cdot \mathbf{r}_v)^2) \end{aligned}$$

Or in different form as

$$dA = \sqrt{EG - F^2} du dv$$

Example II: Let's compute the area of a region on the hyperbolic paraboloid. The region is bounded by positive u and v axes and a quarter circle $u^2 + v^2 = 1$ as shown.

Solution: Again

$$\mathbf{r}_u = (1, 0, v)^T, \mathbf{r}_v = (0, 1, u)^T$$

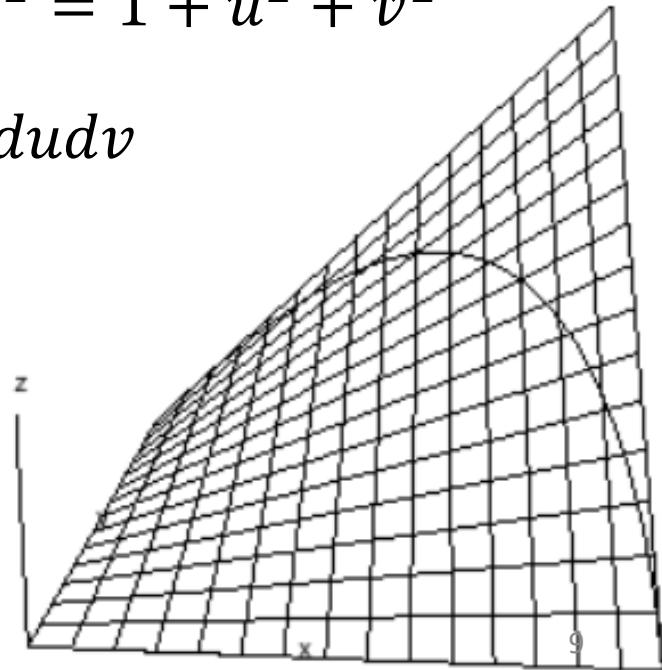
$$E = \mathbf{r}_u \cdot \mathbf{r}_u = 1 + v^2, G = \mathbf{r}_v \cdot \mathbf{r}_v = 1 + u^2, F = \mathbf{r}_u \cdot \mathbf{r}_v = uv$$

$$EG - F^2 = (1 + v^2)(1 + u^2) - u^2v^2 = 1 + u^2 + v^2$$

$$\therefore A = \int_D \sqrt{1 + u^2 + v^2} du dv$$

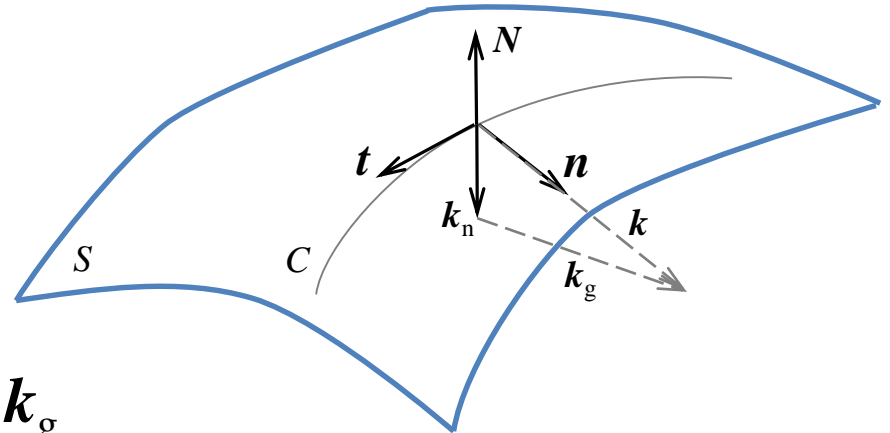
Letting $u = r \cos \theta$ and $v = r \sin \theta$

$$A = \int_0^{\frac{\pi}{2}} \int_0^1 r \sqrt{1 + r^2} dr d\theta = \frac{\pi}{6} (\sqrt{8} - 1)$$



Second Fundamental Form II (Curvature)

- To quantify the curvature of a surface S , we consider a curve C on S which pass through the point p .
- The unit tangent vector t and the unit normal vector n of the curve C are related by



$$\mathbf{k} = d\mathbf{t}/ds = k\mathbf{n} = \mathbf{k}_n + \mathbf{k}_g$$

where \mathbf{k}_n is the **normal curvature** vector and \mathbf{k}_g is the **geodesic curvature** vector.

\mathbf{k}_g : the component of \mathbf{k} in the direction perpendicular to t in the surface tangent plane

\mathbf{k}_n : the component of \mathbf{k} in the surface normal direction

$\mathbf{k}_n = k_n \mathbf{N}$, where k_n - the **normal curvature** of surface at p in t direction. 10

Second Fundamental Form II (cont.)

By differentiating $\mathbf{N} \cdot \mathbf{t} = 0$ along the curve with respect to s , we have

$$\frac{d\mathbf{t}}{ds} \cdot \mathbf{N} + \mathbf{t} \cdot \frac{d\mathbf{N}}{ds} = 0$$

Thus

$$\begin{aligned} k_n &= \frac{d\mathbf{t}}{ds} \cdot \mathbf{N} = -\mathbf{t} \cdot \frac{d\mathbf{N}}{ds} = -\frac{d\mathbf{r}}{ds} \cdot \frac{d\mathbf{N}}{ds} \\ &= \frac{Ldu^2 + 2Mdudv + Ndv^2}{Edu^2 + 2Fdudv + Gdv^2} \end{aligned}$$

$$\begin{aligned} \because d\mathbf{r} &= \mathbf{r}_u du + \mathbf{r}_v dv \\ d\mathbf{N} &= \mathbf{N}_u du + \mathbf{N}_v dv \\ \therefore d\mathbf{r} \cdot d\mathbf{N} &= (\mathbf{r}_u \cdot \mathbf{N}_u) du^2 \\ &+ (\mathbf{r}_u \cdot \mathbf{N}_v + \mathbf{r}_v \cdot \mathbf{N}_u) dudv \\ &+ (\mathbf{r}_v \cdot \mathbf{N}_v) dv^2 \end{aligned}$$

with

$$L = -\mathbf{r}_u \cdot \mathbf{N}_u,$$

$$N = -\mathbf{r}_v \cdot \mathbf{N}_v,$$

$$M = -\frac{1}{2}(\mathbf{r}_u \cdot \mathbf{N}_v + \mathbf{r}_v \cdot \mathbf{N}_u) = -\mathbf{r}_u \cdot \mathbf{N}_v = -\mathbf{r}_v \cdot \mathbf{N}_u$$

Second Fundamental Form II (cont.)

- Since \mathbf{r}_u and \mathbf{r}_v are perpendicular to \mathbf{N} , we have

$$\mathbf{r}_u \cdot \mathbf{N} = 0 \quad \Rightarrow \quad \mathbf{r}_{uu} \cdot \mathbf{N} + \mathbf{r}_u \cdot \mathbf{N}_u = 0 \quad (\text{for } L)$$

$$\mathbf{r}_v \cdot \mathbf{N} = 0 \quad \Rightarrow \quad \mathbf{r}_v \cdot \mathbf{N}_u + \mathbf{r}_{uv} \cdot \mathbf{N} = 0 \quad (\text{for } M)$$

$$\mathbf{r}_v \cdot \mathbf{N} = 0 \quad \Rightarrow \quad \mathbf{r}_{vv} \cdot \mathbf{N} + \mathbf{r}_v \cdot \mathbf{N}_v = 0 \quad (\text{for } N)$$

hence: $L = \mathbf{r}_{uu} \cdot \mathbf{N}$, $M = \mathbf{r}_{uv} \cdot \mathbf{N}$, $N = \mathbf{r}_{vv} \cdot \mathbf{N}$

- We define the second fundamental form II as

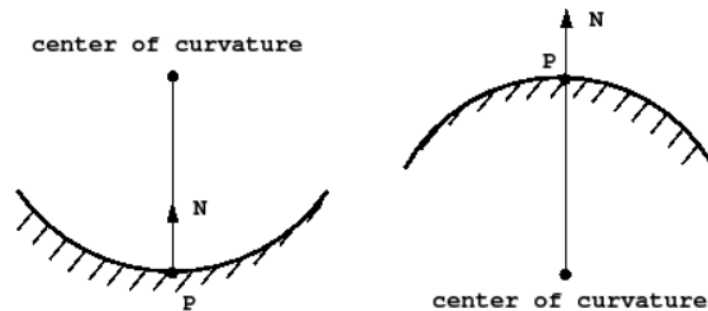
$$II = Ldu^2 + 2Mdudv + Ndv^2$$

and L , M , N are called **second fundamental form coefficients**

$$k_n = \frac{II}{I} = \frac{L + 2M\lambda + N\lambda^2}{E + 2F\lambda + G^2}$$

where $\lambda = \frac{dv}{du}$ is the direction of the tangent line to C at p .

- **Theorem:** All curves lying on a surface S passing through a given point $\mathbf{p} \in S$ with the same tangent line have the same normal curvature at this point.
- Note that, sometimes the positive normal curvature is defined in the **opposite** direction.

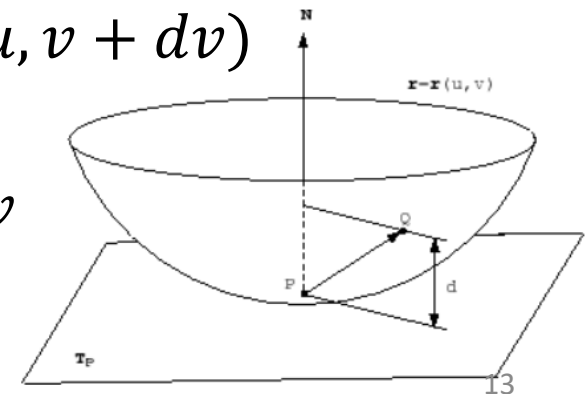


- We now start to study the **local surface property** by II.
- Suppose two neighboring points \mathbf{P} and \mathbf{Q} on S

$$\mathbf{P} = \mathbf{r}(u, v) \quad \text{and} \quad \mathbf{Q} = \mathbf{r}(u + du, v + dv)$$

By Taylor expansion, we have

$$\mathbf{r}(u + du, v + dv) = \mathbf{r}(u, v) + \mathbf{r}_u du + \mathbf{r}_v dv + \frac{1}{2} (\mathbf{r}_{uu} du^2 + 2\mathbf{r}_{uv} du dv + \mathbf{r}_{vv} dv^2) + \dots$$



- Projecting the vector:

$$\begin{aligned} \mathbf{PQ} &= \mathbf{r}(u + du, v + dv) - \mathbf{r}(u, v) \\ &= \mathbf{r}_u du + \mathbf{r}_v dv + \frac{1}{2} (\mathbf{r}_{uu} du^2 + 2\mathbf{r}_{uv} dudv + \mathbf{r}_{vv} dv^2) + \dots \end{aligned}$$

onto \mathbf{N} by using the second fundamental form, we have

$$\mathbf{PQ} \cdot \mathbf{N} = (\mathbf{r}_u du + \mathbf{r}_v dv) \cdot \mathbf{N} + \frac{1}{2} II = \frac{1}{2} II$$

($\because \mathbf{r}_u \cdot \mathbf{N} = \mathbf{r}_v \cdot \mathbf{N} = 0$)

where the higher order terms are neglected.

- In conclusion, the **local shape variation**:

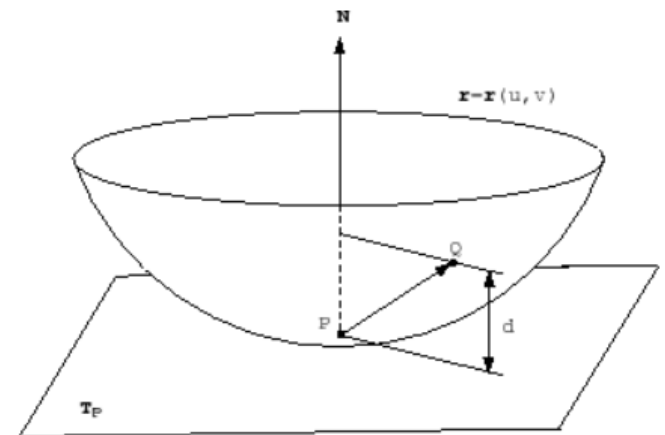
$$d = II / 2$$

When $d = 0$, it become

$$Ldu^2 + 2Mdudv + Ndv^2 = 0$$

which can be considered as a quadratic equation in terms of du, dv .

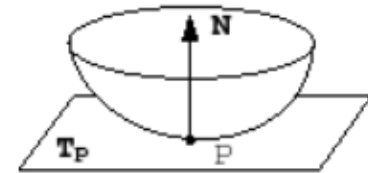
$$du = \frac{-M \pm \sqrt{M^2 - LN}}{L} dv \quad (\text{Assuming } L \neq 0)$$



Local Shape Analysis by Second Fundamental Form II

- $M^2 - LN < 0$, this is **no real root**: No intersection between $\mathbf{r}(u,v)$ and T_p except the point p .

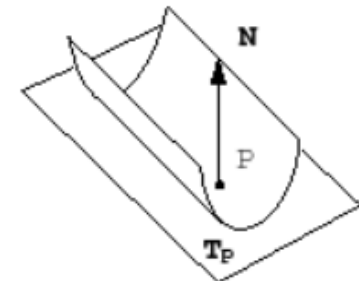
➔ An **elliptic** point



- $M^2 - LN = 0$ and $L^2 + M^2 + N^2 \neq 0$, there are **double roots**: The surface intersects T_p with one line

$$du = -\frac{M}{L} dv$$

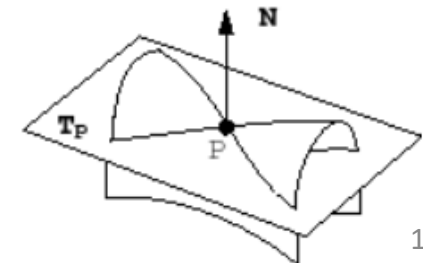
➔ A **parabolic** point



- $M^2 - LN > 0$, there are **two roots**: The surface intersects its tangent plane with two lines

$$du = \frac{-M \pm \sqrt{M^2 - LN}}{L} dv$$

➔ A **hyperbolic** point



Local Shape Analysis by Second Fundamental Form II (cont.)

- $L = M = N = 0$, the surface and the tangent plane have a contact of **higher order** than in the above cases at the point p .
⇒ A flat or **planar** point
- If $L = 0$ and $N \neq 0$, we can solve for dv instead of du .
- If $L = N = 0$ and $M \neq 0$, we have $2Mdudv = 0$, thus the intersection lines will be the two iso-parametric lines:

$$u = \text{const}1 \quad v = \text{const}2$$

Principal Curvatures

- From the second fundamental form, we already know

$$k_n = \frac{II}{I} = \frac{L+2M\lambda+N\lambda^2}{E+2F\lambda+NG^2}$$

The normal curvature at \mathbf{p} depends on the direction of $\lambda = \frac{dv}{du}$.

- The extreme value of k_n can be obtained by solving: $dk_n/d\lambda = 0$.
 $(E + 2F\lambda + G\lambda^2)(N\lambda + M) - (L + 2M\lambda + N\lambda^2)(G\lambda + F) = 0$

$$k_n^e = \frac{L+2M\lambda+N\lambda^2}{E+2F\lambda+G\lambda^2} = \frac{N\lambda+M}{G\lambda+F}$$

- Furthermore, since $E + 2F\lambda + G\lambda^2 = (E + F\lambda) + \lambda(F + G\lambda)$ and $L + 2M\lambda + N\lambda^2 = (L + M\lambda) + \lambda(M + N\lambda)$, we have
→ $((E + F\lambda) + \lambda(F + G\lambda))(N\lambda + M) = ((L + M\lambda) + \lambda(M + N\lambda))(G\lambda + F)$
→ $(E + F\lambda)(N\lambda + M) = (L + M\lambda)(G\lambda + F)$

- Therefore, we have

$$k_n^e = \frac{L + 2M\lambda + N\lambda^2}{E + 2F\lambda + G\lambda^2} = \frac{M + N\lambda}{F + G\lambda} = \frac{L + M\lambda}{E + F\lambda}$$

- Substituting $\lambda = \frac{dv}{du}$, we have

$$(L - k_n^e E)du + (M - k_n^e F)dv = 0$$

$$(M - k_n^e F)du + (N - k_n^e G)dv = 0$$

This is a **homogeneous linear system** of equations for du , dv , which will have a nontrivial solution if and only if

$$\begin{vmatrix} L - k_n^e E & M - k_n^e F \\ M - k_n^e F & N - k_n^e G \end{vmatrix} = 0$$

$$(EG - F^2)k_n^{e2} - (EN + GL - 2FM)k_n^e + (LN - M^2) = 0$$

- The discriminant of D of this quadratic equation in k_n^e can be

$$D = 4 \left(\frac{EG - F^2}{E^2} \right) (EM - FL)^2 + \left(EN - GL - \frac{2F}{E} (EM - FL) \right)^2$$

Since $EG - F^2 \geq 0$, we have $D \geq 0$. The quadratic equation has **real roots**.

- If we set

$$K = \frac{LN - M^2}{EG - F^2} \quad \text{and} \quad H = \frac{EN + GL - 2FM}{2(EG - F^2)}$$

The quadratic equation is simplified to

$$k_n^e{}^2 - 2Hk_n^e + K = 0$$

which has the following solutions

$$k_{\max} = H + \sqrt{H^2 - K}$$

$$k_{\min} = H - \sqrt{H^2 - K}$$

- k_{\max} and k_{\min} are defined as the **maximum** and **minimum** principal curvature.
- The directions for which give k_{\max} and k_{\min} are called principal directions, the corresponding directions in uv-plane

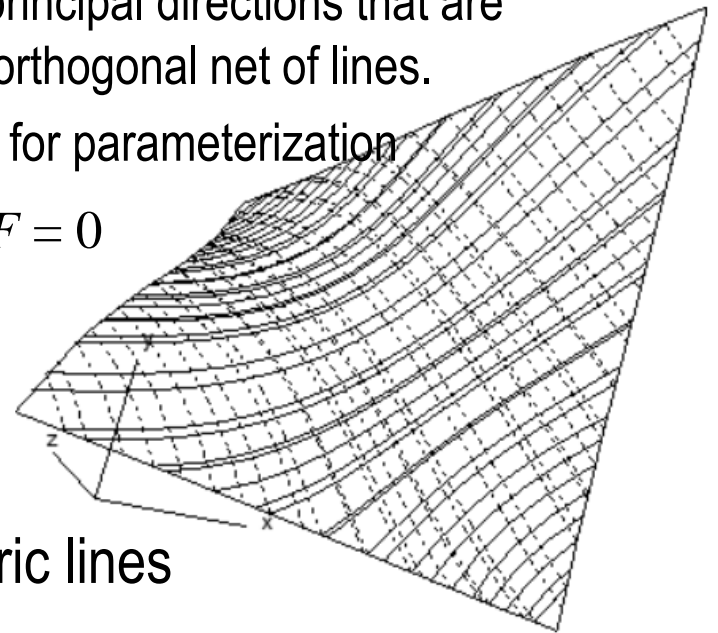
$$\lambda = -\frac{M - k_n F}{N - k_n G} \quad \text{or} \quad -\frac{L - k_n E}{M - k_n F}$$

by replacing k_n with either k_{\max} or k_{\min} .

- When $H^2 = K$, k_n is a double root with value equal to H and the corresponding point of the surface is an **umbilical** point.
 - At an umbilical point, a surface is locally a part of sphere with radius of curvature: $1 / H$
 - In the special case – both K and H vanish, the point is a flat or planar point
- A curve on surface where tangent at each point is in a principal direction at that point is called a line of curvature
 - At each (non-umbilical) point, there are two principal directions that are orthogonal – the lines of curvatures form an orthogonal net of lines.
 - We can try to use this orthogonal net of lines for parameterization
 - Let $\cos \omega = \cos \frac{\pi}{2} = 0$ (page 7), we have $F = 0$
 - We can then from the equation of λ have

$$(L - k_n E)du + Mdv = 0$$

$$Mdu + (N - k_n G)dv = 0$$
- The **necessary condition** for the parametric lines to be line of curvature is: $F = M = 0$.



Line of curvatures

Gaussian and Mean Curvatures

- From above equation on page 19, we can easily have

$$K = k_{\max}k_{\min}$$
$$H = (k_{\min} + k_{\max})/2$$

- The sign of the Gaussian curvature coincides with the sign of $LN - M^2$, since $K = \frac{LN - M^2}{EG - F^2}$ and $EG - F^2 > 0$. Then, we have
 1. $K > 0$, the surface is elliptic at the point;
 2. $K < 0$, the surface is hyperbolic at the point;
 3. $K = 0$ and $H \neq 0$, the surface is parabolic at the point;
 4. $K = 0$ and $H = 0$, the surface is flat (or planar) at the point.
- This is good for segmenting an given surface to different regions (reverse engineering of CAD models).

Euler's Theorem

- The normal curvature of a surface in an arbitrary direction (in the tangent plane) at point \mathbf{p} can be expressed in terms of principal curvatures k_1 and k_2 at point \mathbf{p} and the angle between the arbitrary direction and the principal direction corresponding to k_1 as:

$$k_n(\phi) = k_1 \cos^2 \phi + k_2 \sin^2 \phi$$